USER MANUAL

PANMIN: Sequential and Parallel Global Optimization Procedures with a variety of options for the Local Search Strategy.

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http://merlin.cs.uoi.gr/panmin

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1 Merlin Set-Up

Before running the global optimization codes, one should install properly the MERLIN optimization package [1, 2].

1.1 Merlin installation

The following instructions are valid for installing Merlin under a Unix system.

- 1. Download the latest MERLIN package from http://merlin.cs.uoi.gr. The corresponding file will be of the form merlin-x.y.tar.gz where x.y is the MERLIN version.
- $2.\ \, {\rm Uncompress}$ and untar the file

tar xvfz merlin-x.y.tar.gz

A directory named merlin-x.y will be created.

- 3. Change into the newly created directory cd merlin-x.y
- 4. Edit Makefile.inc and provide appropriate values for the variables DESTDIR and FOPTIONS (found in the first few lines of Makefile.inc).

DESTDIR is the destination directory where the MERLIN binaries and accompanying files will be installed. You must specify DESTDIR using a full path. Note that this directory must be different from the directory where you unpacked the MERLIN sources. Also note that if installing MERLIN outside your home directory you must have super-user privileges. Example:

DESTDIR=/usr/local/merlin

FOPTIONS is a string of options that must be passed to the Fortran compiler during the installation process. This is a good place to pass appropriate optimization options to the compiler. Example:

FOPTIONS=-03

In addition the following options may be set:

LINKOPTIONS: Options that must be passed to the linker during installation.

TYPE: This specifies whether MERLIN will be compiled using REAL or DOUBLE PRECISION arithmetic

MXV: The maximum number of optimization parameters Merlin will handle.

MXT: The maximum number of terms in a sum-of-squares objective function.

MCLBUF: The maximum size (in bytes) of a compiled MCL program.

MCLMEM: The maximum size (in words) of memory available to MCL programs.

The default values provided for DESTDIR and FOPTIONS are adequate for most systems.

Note for Cygwin users: You must set F77=g77 and uncomment EXESUFFIX=.exe in Makefile.inc.

- 5. Build the package make
- 6. Install the package make install

1.2 Running Merlin

In order to compile the user written subprograms with the rest of the MERLIN package one must use the run-merlin script. After installation, the run-merlin script as well as other binaries are located in DESTDIR/bin. Hence one needs to add this directory to its Unix PATH.

To add DESTDIR/bin to your Unix path and assuming that DESTDIR is set to /usr/local/merlin:

- Users of csh and tcsh add the following line in the file .cshrc path = (\$path /usr/local/merlin/bin)
- Users of sh add the following lines in the file .profile PATH=\$PATH:/usr/local/merlin/bin EXPORT PATH
- Users of bash add the following lines in the file .bashrc PATH=\$PATH:/usr/local/merlin/bin EXPORT PATH

Alternatively you can invoke the run-merlin script using a full path. For example: /usr/local/merlin/bin/run-merlin funmin.f

The run-merlin script accepts one or more file names as arguments that can be of the following types:

- Files ending in .d These are files that must be processed by the MERLIN preprocessor before they can be compiled. The MERLIN preprocessor will use the definitions file DEFS in the current directory, or if no such file exists, the one used for the installation of the MERLIN package (found in DESTDIR/files). After preprocessing the files, the script will compile and link them with the rest of the MERLIN package.
- Files ending in .f
 These are files containing Fortran-77 code that must be compiled.
- Files ending in . o
 These are files containing object code (already compiled).

In addition the run-merlin script recognizes the following environment variables.

MERLIN_F77

This is the name of the compiler that will be used to compile the user written code.

• MERLIN_FOPTIONS

Options that will be used when compiling the user written code. The default is to use -c (compile only-do not link) and any other flags that were specified when editing Makefile.inc. Note that if you set this environment variable you must include the -c compiler flag.

• MERLIN_LDOPTIONS

Options that will be passed to the linker when building the final MERLIN executable. Here you can specify any libraries required by the user written subprograms.

2 Running and customizing the global optimization codes

2.1 Some general remarks

Before running any of the global optimization codes, make sure you have installed the latest version of the Merlin optimization package as described in section 1.1.

In addition, you should prepare the objective function following the instructions given in the Merlin Users Manual. You may prepare either FUNCTION FUNMIN or SUBROUTINE SUBSUM. Optionally the gradient vector, Hessian and Jacobian matrices may be programmed as well.

2.2 Running PRICE

1. Prepare the input file. This file must be named PRICE. DAT. A sample file is displayed below.

2	NOD
0	NOF
10000	NOC
1.0000000000000E-04	EPS
10000.00000000	OMEGA
20	NF
1	IPRINT
1	NFORM
PRICE.OUT	OUTFIL
POIMAR.DAT	POIFIL
in.dat	FINP
out.dat	FOUT

Only the first column is required by the software. The second column contains only code-names that serve as a reminder to the user to ease the data entry.

- (a) NOD is the dimensionality of the problem.
- (b) NOF is the number of terms when the SUBROUTINE SUBSUM has been prepared. If NOF is set to zero, FUNCTION FUNMIN is used.
- (c) NOC is an upper bound for the number of function evaluations.
- (d) EPS is a small tolerance, used to terminate the search.
- (e) OMEGA is the value of the ω parameter.
- (f) NF is an integer used to set the sample size M via the relation: $M = NF \times NOD$
- (g) IPRINT is a flag. If it is set to zero, no intermediate printout is produced. If it is set to one, informative printout is issued at every iteration.
- (h) NFORM controls the format of the final output. Takes on the values 0,1,2 and the corresponding formats are described at the end of this section.
- (i) OUTFIL is a character string that specifies the name of the output file.
- (j) POIFIL is a character string that specifies the name of the file containing an initial point, parameter bounds and the fix-status as described in section 2.8.2.
- (k) FINP is a character string that specifies the name of the Merlin instructions file as described in section 2.8.1. If FINP is left blank then the final polishing is not performed.
- (1) FOUT is a character string that specifies the name of the Merlin output file.
- 2. Prepare the Merlin input file as described in section 2.8.1.
- 3. Prepare a file containing the parameter bounds as described in section 2.8.2.
- 4. Compile the program and the objective function, link with the rest of the MERLIN package and run (assuming the objective function is in file funmin.f): run-merlin price.d funmin.f
- 5. After the run completes, the results are disposed in the output file. Its file name is specified in the input file PRICE.DAT (The default being PRICE.OUT). The output file contains the values of the minimization parameters along with the corresponding value of the objective function. Three output formats are supported and may be specified in the input file (NFORM).
 - NFORM=0 Raw unformatted output.

 Output is written using unformatted write statements as in the following program segment:

```
DO 10, I=1, N

WRITE (1) X(I)

CONTINUE

WRITE (1) VALUE
```

• NFORM=1 Raw formatted output.

Output is written using formatted write statements as in the following program segment:

• NFORM=2 Output is written as a Merlin record. This is the default.

2.3 Customizing PRICE

The following parameter statement is used to customize the code, in accord with the problem at hand.

• PARAMETER (MAXFAC = 100)
This sets the maximum value for the NF factor.

2.4 Running TML

1. Prepare the input file. This file must be named TML. DAT. A sample file is displayed below.

2	NOD
0	NOF
10	ITTHR
5.000000000000	HEAL
2	NEARN
100	NSAMPL
4.0000000000000	SIGMA
0.99500000000000	COVTHR
0.1000000000000E-01	XDEPS
0.1000000000000E-03	FDEPS
0.1000000000000E-02	GDEPS
0	IREST
100	NDUMP
in.dat	FINP
out.dat	FOUT
MINIMA	FMIN
POIMAR.DAT	POIFIL
input	INDIR

Only the first column is required by the software. The second column contains only code-names that serve as a reminder to the user to ease the data entry.

- (a) NOD is the dimensionality of the problem.
- (b) NOF is the number of terms, in case where the SUBROUTINE SUBSUM is being prepared.
 - If NOF is set to zero, FUNCTION FUNMIN is used.
- (c) ITTHR is the enforced minimum number of iterations of the algorithm.
- (d) HEAL is the healing parameter.
- (e) NEARN specifies the number of nearest neighbors
- (f) NSAMPL specifies the sample size
- (g) SIGMA specifies the σ parameter involved in the calculation of the critical distance.
- (h) COVTHR specifies the required relative domain coverage. (Default value: 0.995)
- (i) XDEPS specifies the minimum distance between two minima to be considered as different.
- (j) FDEPS specifies the minimum relative difference in the values of two minima, in order to be considered as different.
- (k) GDEPS specifies the maximum value for the RMS gradient, in order that a point is accepted as a local minimum.
- (l) IREST If set to a non-zero value, starts the procedure from a previously saved dump.
- (m) NDUMP Specifies the iteration period between dumps.
- (n) FINP is a character string that specifies the name of the Merlin instructions file as described in section 2.8.1.
- (o) FOUT is a character string that specifies the name of the Merlin output file.
- (p) FMIN is a character string that specifies the name of the file containing the discovered local minima.
- (q) POIFIL is a character string that specifies the name of the file containing an initial point, parameter bounds and the fix-status as described in section 2.8.2.
- (r) INDIR is a character string that specifies the name of a Unix directory, where auxiliary files may reside as described in section 2.6. This applies only to the parallel version of the software. The sequential version ignores it.
- 2. Prepare a file containing the parameter bounds as described in section 2.8.2.
- 3. Prepare the Merlin input file as described in section 2.8.1.
- 4. Compile the program and the objective function, link with the rest of the MERLIN package and run (assuming the objective function is in file funmin.f): run-merlin tml.d funmin.f

5. After the run completes, the results are disposed in the output file. Its file name is specified in the input file TML.DAT, the default being MINIMA). The output file contains the values of the minimization parameters along with the corresponding value of the objective function, and is written as a series of MERLIN records (see the MERLIN Users Manual for a description of MERLIN records).

2.5 Customizing TML

The following parameter statements are used to customize the code, in accord with the problem at hand.

- PARAMETER (MXNM = 10000)
 - Sets the maximum number of local minima that will be stored. (The program stops when the number of discovered minima becomes equal to MXNM).
- PARAMETER (MXNS = 500)

The maximum number of points to sample at each iteration. (Maximum allowed value for the NSAMPL input parameter).

• PARAMETER (MXNNN = 8)

The maximum number of nearest neighbors considered. (Maximum allowed value for the NEARN input parameter).

2.6 Running Parallel-TML (PTML)

- 1. Prepare the input file. The file name and contents are the same as for the plain TML code. (section 2.4).
- 2. Prepare a file containing the parameter bounds as described in section 2.8.2.
- 3. Prepare the MERLIN input file as described in section 2.8.1.
- 4. In parallel TML, it is necessary for every processor to operate on a separate directory of the file system, so that intermediate files created by MERLIN and the objective function do not get mixed up. The user must create a directory and copy all input files required by MERLIN and the objective function in this directory. Note that the MERLIN panel description file PDESC must be copied as well.

```
mkdir input
cp PDESC input
cp an_input_file input
```

5. Create temporary directories for all processors and copy the necessary input files (assuming 4 processors).

```
create-ptml-dirs 4 input
```

6. Compile the program and the objective function and link with MERLIN and the MPI environment (assuming the objective function is in file funmin.f):

```
setenv MERLIN_F77 mpif77
compile-merlin ptml.d funmin.f
```

- 7. Run the program (assuming 4 processors): mpirun -np 4 merlin.executable
- 8. The results are disposed in the output file (its file name is specified in the input file TML.DAT, the default being MINIMA).

2.7 Customizing PTML

The following parameter statements are used to customize the code, in accord with the problem at hand. These statements reside in the include file ptml.h.

- PARAMETER (MXPROC = 100)

 The maximum number of processors that can be utilized.
- PARAMETER (MXNM = 10000)

 Sets the maximum number of local minima that will be stored. (The program stops when the number of discovered minima becomes equal to MXNM).
- PARAMETER (MXNS = 500)

 The maximum number of points to sample at each iteration. (Maximum allowed value for the NSAMPL input parameter).
- PARAMETER (MXNNN = 8)

 The maximum number of nearest neighbors considered. (Maximum allowed value for the NEARN input parameter).

2.8 Files common to all methods

2.8.1 The Merlin input file

The Merlin input file contains commands that are to be executed by Merlin in order to perform a local minimization. The name of this file is specified in files PRICE.DAT or TML.DAT according to the method, the default being in.dat. A sample is presented below:

```
anal bfgs noc 5000
```

Note that it not allowed to change the current point using commands such as point, init etc. Note also that this may be the object file of an MCL program.

2.8.2 Specifying parameter bounds

The name of this file is specified in files PRICE.DAT or TML.DAT according to the method, the default being POIMAR.DAT. Each line in the file corresponds to one of the minimization parameters and must contain 4 values: An initial value for the parameter, the lower and upper bound and an integer specifying whether the parameter is fixed (0) or not (1). Example (for a two parameter objective function):

Note that if you attempt to run any of the global optimization codes without preparing this file, the program will create a sample file with default values and stop. You must then edit the file, specify the correct values for your problem, and rerun the program.

3 Test Runs

We employ for the test runs the "Six-hump Camel-Back" function:

$$f(x,y) = (4 - 2.1x^{2} + \frac{1}{3}x^{4})x^{2} - 4(1 - y^{2})y^{2} + xy$$

This function has six local minima, two of which are global. The code for the function and its gradient is given in section 3.1. The PRICE and the TML results are presented in sections 3.2 and 3.3 correspondingly. In section 4.2 we list a code that makes use of the subroutine OPTIMA to search for the global minimum of the same test function. The simplistic multistart approach is being used, i.e. we generate a number of points at random and from each one we start a local search.

3.1 Six Hump Camel-Back code

The code for the "Six-hump Camel-Back", its gradient and its Hessian, is given below:

```
FUNCTION FUNMIN ( X,N )

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

DIMENSION X(N)

X1 = X(1)

X2 = X(2)

FUNMIN = (4 - 2.1*X1**2 + X1**4/3)*X1**2 +

& X1*X2 + (-4 + 4*X2**2)*X2**2

END
```

3.2 PRICE - Test Run

To execute the test run, issue the following command: run-merlin price.d 6hump.f The following output is produced on the standard output.

```
PRICE running with ...
Number of parameters:
                            2
Maximum function calls: 10000
Termination criterion: 1.0000E-04
Weighting factor:
                        1.0000E+04
Sample size factor:
                           20
Printout option:
                            1
Output file:
                     PRICE.OUT
Bounds file:
                     POIMAR.DAT
Merlin input file:
                     in.dat
Merlin output file: out.dat
```

Output format:

```
      Iter: 30
      Lower value: -0.14170040690117
      Calls: 82 of 10000

      Iter: 35
      Lower value: -0.22434743776021
      Calls: 92 of 10000

      Iter: 48
      Lower value: -0.64718662239411
      Calls: 111 of 10000

      Iter: 115
      Lower value: -0.72788366844541
      Calls: 199 of 10000

      Iter: 140
      Lower value: -0.83495615401031
      Calls: 239 of 10000

      Iter: 141
      Lower value: -1.0275395980524
      Calls: 241 of 10000
```

1

 Iter:
 211
 Lower value:
 -1.0277942972752
 Calls:
 352 of 10000

 Iter:
 239
 Lower value:
 -1.0284090174387
 Calls:
 390 of 10000

 Iter:
 257
 Lower value:
 -1.0313613560203
 Calls:
 408 of 10000

 Iter:
 312
 Lower value:
 -1.0313833436910
 Calls:
 463 of 10000

 Iter:
 335
 Lower value:
 -1.0316284204941
 Calls:
 486 of 10000

The termination criterion has been satisfied Function value: -1.0316284534837

Total function evaluations: 661 PRICE Iterations: 480

The minimum has been refined by Merlin, GRMS = 3.92365572601884E-10

Output parameters in file: PRICE.OUT

The relevant input files are listed:

File: POIMAR.DAT

File: PRICE.DAT

2	NOD
10000	NOC
1.0000000000000E-04	EPS
10000.000000000	OMEGA
20	NF
1	IPRINT
1	NFORM
PRICE.OUT	OUTFIL
POIMAR.DAT	POIFIL
in.dat	in.dat
out.dat	out.dat

File: in.dat

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File: PRICE.OUT (Contains the global minimizer).

- 8.98420130599726E-02
- -0.71265640298440
- -1.0316284534837

3.3 TML - Test Run

To execute the test run, issue the following command: run-merlin tml.d 6hump.f
The following output is produced on the standard output.

TML running with ... Iteration threshold: 10 Healing parameter: Number of nearest neighbors: 2 Sample size: 100 Sigma parameter: 4. 0.995000005 Coverage threshold: X distance criterion: 0.01 F distance criterion: 0.0001 Gradient convergence criterion: 0.001 Saving every 100 iterations Merlin input file: Merlin output file: out.dat

... The first minimum is found ... F: 136 G: 10 Coverage: 0.79865 Iterations: 1 Est. minima: 3.9 Iterations: 2 Coverage: 0.96460 Est. minima: 1.4 G: ... Number of minima found: F: 361 32 ... Number of minima found: 3 F: 375 G: 46 Iterations: 3 Coverage: 0.95274 Est. minima: 4.0 G: ... Number of minima found: 4 F: 489 60 Est. minima: 5.0 Iterations: 4 Coverage: 0.97160 ... Number of minima found: 5 G: 124 Iterations: 5 Coverage: 0.98355 Est. minima: 5.8 Iterations: 6 Coverage: 0.99071 Est. minima: 5.6 1042 G: 299 ... Number of minima found: 6 Coverage: 0.99201 Iterations: 7 Est. minima: 6.6 Iterations: 8 Coverage: 0.99516 Est. minima: 6.5 Coverage: 0.99674 Est. minima: 6.4 Iterations: 9 Iterations: 10 Coverage: 0.99769 Est. minima: 6.3

TML run completed.

Number of local minimizers found: 6

The minimizers are disposed to file: MINIMA

Total number of Function calls: 1914
Total number of Gradient calls: 838
Total number of Jacobian calls: 0
Total number of Hessian calls: 0

Total number of local optimizations: 51 Maximum number of starting points: 13 Current state has been saved.

The relevant input files are listed:

File: POIMAR.DAT

$File:\ \underline{\texttt{TML.DAT}}$

2	NOD
0	NOF
10	ITTHR
5.000000000000	HEAL
2	NEARN
100	NSAMPI
4.0000000000000	SIGMA
0.99500000476837	COVTHE
0.1000000000000E-01	XDEPS
0.1000000000000E-03	FDEPS
0.1000000000000E-02	GDEPS
0	IREST
100	NDUMP
in.dat	FINP
out.dat	FOUT
MINIMA	FMIN
POIMAR.DAT	POIFII
input	INDIR

File: <u>in.dat</u>

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File: MINIMA (Contains the minimizers found).

2

1)	8.9842012988325989E-02	-5.000	5.000
2)	0.7126564030053476	-5.000	5.000
Value	-1.031628453483664		
1)	8.9842001740361430E-02	-5.000	5.000

2)	0.7126564016386691	-5.000	5.000
	Value1.031628453483664		
1)	1.703606615756318	-5.000	5.000
2)	0.7960835641969248	-5.000	5.000
	Value0.2154630210843795		
1)	1.703606616107386	-5.000	5.000
2)	0.7960835644085253	-5.000	5.000
	Value0.2154630210843795		
1)	1.607104586736009	-5.000	5.000
2)	0.5686514769482340	-5.000	5.000
	Value 2.104250946486463		
1)	1.607104589746949	-5.000	5.000
2)	0.5686514782893214	-5.000	5.000
	Value 2.104250946486463		

3.4 PTML - Test Run

The test run assumes that LAM-MPI is installed and operational. The test run uses 4 processors. To execute the test run, issue the following commands:

```
../../src/create-ptml-dirs 4 indir
setenv MERLIN_F77 mpif77
compile-merlin ptml.d 6hump.f
lamboot
mpirun -np 4 merlin.executable
wipe
```

The following output is produced on the standard output.

Parallel TML running with ... Iteration threshold: 10

Healing parameter: 5.000000000000

Number of nearest neighbors: 2

Sample size: 100

Gradient convergence criterion: 1.00000000000D-03

Saving every 100 iterations Merlin input file: in.dat Merlin output file: out.dat

Directory containing input files: indir

... The first minimum is found ... 136 G: Iterations: 1 Coverage: 0.6350206 Est. minima: 2.0 Iterations: 2 Coverage: 0.9556767 Est. minima: 1.5 ... Number of minima found: G: F: 379 31 ... Number of minima found: 3 407 G: 47 F: Iterations: 3 Coverage: 0.9476247 Est. minima: 4.1 ... Number of minima found: 546 G: 75 Iterations: 4 Coverage: 0.9706831 Est. minima: 5.0 ... Number of minima found: 5 F: 723 G: 130 Iterations: 5 Coverage: 0.9820669 Est. minima: 5.9 ... Number of minima found: F: 1039 G: 282 Coverage: 0.9870537 Est. minima: 6.8 Iterations: 6 Iterations: 7 Coverage: 0.9917658 Est. minima: 6.7 Coverage: 0.9953168 Est. minima: 6.5 Iterations: 8 Iterations: 9 Coverage: 0.9968641 Est. minima: 6.4 Iterations: 10 Coverage: 0.9978384 Est. minima: 6.3

PTML run completed.

Number of local minimizers found: 6

The minimizers are disposed to file: MINIMA

Total number of Function calls: 2400
Total number of Gradient calls: 986
Total number of Jacobian calls: 0
Total number of Hessian calls: 0
Total number of local optimizations: 0
Maximum number of starting points: 13

Current state has been saved.

Processor Utilization

Proc	Minim	Graph	Fcalls	Gcalls
0	0	0	1246	0
1	20	346	375	318
2	20	346	374	320
3	20	346	405	348

The relevant input files are listed:

File: POIMAR.DAT

File: TML.DAT

2 NOD

0	NOF
10	ITTHR
5.000000000000	HEAL
2	NEARN
100	NSAMPL
4.0000000000000	SIGMA
0.99500000476837	COVTHR
0.1000000000000E-01	XDEPS
0.1000000000000E-03	FDEPS
0.1000000000000E-02	GDEPS
0	IREST
100	NDUMP
in.dat	FINP
out.dat	FOUT
MINIMA	FMIN
POIMAR.DAT	POIFIL
indir	INDIR

File: <u>in.dat</u>

ANAL

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File: MINIMA (Contains the minimizers found).

2			
1)	8.9842012988325989E-02	-5.000	5.000
2)	0.7126564030053476	-5.000	5.000
	Value1.031628453483664		
1)	8.9842001740361430E-02	-5.000	5.000
2)	0.7126564016386691	-5.000	5.000
	Value1.031628453483664		
1)	1.703606615756318	-5.000	5.000
2)	0.7960835641969248	-5.000	5.000
	Value0.2154630210843795		
1)	1.703606616107386	-5.000	5.000
2)	0.7960835644085253	-5.000	5.000
	Value0.2154630210843795		
1)	1.607104589746949	-5.000	5.000
2)	0.5686514782893214	-5.000	5.000
	Value 2.104250946486463		
1)	1.607104586736009	-5.000	5.000
2)	0.5686514769482340	-5.000	5.000
	Value 2.104250946486463		

4 Examples

4.1 Polynomial Root-Finder

As an example of an application of OPTIMA, we present a polynomial root finder. The method we use is based on Bairstow's algorithm and is briefly described here. Let $P_n(x) = \sum_{k=0}^n a_k x^k$ be a polynomial of degree n with real coefficients a_k , $k = 0, 1, 2, \dots, n$. The division with a quadratic polynomial

$$P_n(x) = (x^2 + p_1 x + p_2) B_{n-2}(x, p_1, p_2) + R(p_1, p_2) x + Q(p_1, p_2)$$
(1)

can be made perfect, by choosing properly p_1 and p_2 so as to make the remainder terms R and Q vanish. (The coefficients $b_k, k = 0, 1, \dots, n-2$ of B_{n-2} as well as R and Q, are obtained by synthetic division, i.e. via a recursion relation). If we determine such values for p_1 and p_2 then $P_n(x)$ has two roots that coincide with the roots of the quadratic. The same procedure is then applied to the quotient polynomial B_{n-2} and so on so forth. One way to search for proper values of p_1 and p_2 is by optimizing the quantity: $R^2 + Q^2$. It is here where OPTIMA can be used. We list the source code in Fortran 77.

PROGRAM ROOTF

```
*
*
  This is a polynomial root finder program.
  the polynomials must have real coefficients.
   The method applied is a modification of bairstow's
*
   i.e. division by a quadratic polynomial x**2 +p1*x +p2
  determining p1 & p2 to be such that the remainder is vanishing.
   Then a deflation is applied by synthetic division to reduce
  the polynomial degree by two, and the procedure is repeated.
   A check is always made if the degree is reduced to either
   one or two to use special finishing procedure.
*
      IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
      COMMON /TOROOT/ A(0:100), B(0:100), KCO
      COMPLEX ROOT(100), DISC
      PARAMETER ( N = 2, M = 2 )
      DIMENSION ICODE(4), XP(2), XLL(2), XRL(2), IXAT(2)
      CHARACTER LINE*78
      DATA ICODE / 1, 0, 0, 0 /
      DO 100 I=1,78
         LINE(I:I) = '='
100
      CONTINUE
  Read in, tolerance, polynomial degree, polynomial coefficients
      WRITE (*,*) 'Enter a termination tolerance: '
```

```
READ (*,*) EPS
      WRITE (*,*) 'Enter the degree of the polynomial:'
      READ (*,*) KCO
      WRITE (*,*) 'Enter the polynomial coefficients: (a(0),a(1),...)'
      READ (*,*) (A(I), I=0, KCO)
* Type the above input for reference.
      WRITE (*,'(A)') LINE
      WRITE (*,*) ' Running with the following input '
      WRITE (*,*) 'Tolerance: ', eps
      WRITE (*,*) 'Degree: ', kco
                       Coefficients a(i), i=0,1,...,
      WRITE (*,*)'
      WRITE (*,*) (A(I), I=0, KCO)
      WRITE (*,'(A)') LINE
      NOR = 0
      CONTINUE
30
* Check if the degree is one, and if so solve a linear equation.
      IF (KCO.EQ.1) THEN
         WRITE (*,*) 'The roots of the polynomial are:'
         NOR = NOR + 1
         ROOT(NOR) = CMPLX(-A(0)/A(1),0)
         DO 1 I=1,NOR
            WRITE (*,19) I, ROOT(I)
1
         CONTINUE
19
         FORMAT (2X, 'Root # ', i4, t17, '(', g14.7, ', ', g14.7, ')')
         STOP
      END IF
* Check if the degree is two, and if so solve a quadratic equation.
      IF (KCO.EQ.2) THEN
        WRITE (*,*) 'The roots of the polynomial are:'
        NOR = NOR + 1
        DISC = CMPLX(A(1)**2 - 4*A(2)*A(0), 0.D0)
        ROOT(NOR) = (-A(1)+CSQRT(DISC))/2./A(2)
        NOR = NOR + 1
        ROOT(NOR) = (-A(1)-CSQRT(DISC))/2./A(2)
        DO 2 I=1,NOR
           WRITE (*,19) I, ROOT(I)
2
        CONTINUE
        STOP
      END IF
* Initialize randomly in (-1,1)
     P1 = 2*RANM()-1
     P2 = 2*RANM()-1
```

```
XP(1) = P1
     XP(2) = P2
  Minimize the remainder down to zero !!!
     CALL OPTIMA(N,M,XP,XV,XLL,XRL,IXAT,ICODE,
                 'in.dat','/dev/null',GRMS,NF,NG,NHE,NJA)
     IF (SQRT(XV).LE.EPS) THEN
       P1 = XP(1)
       P2 = XP(2)
       DISC = CMPLX(P1**2-4*P2, 0.D0)
       NOR = NOR + 1
       ROOT(NOR) = (-P1 + CSQRT(DISC))/2
       NOR = NOR + 1
       ROOT(NOR) = (-P1 - CSQRT(DISC))/2
       CALL SYNDIV(A, KCO, P1, P2, B, R, Q)
       KCO = KCO - 2
       DO 3 I = 0, KCO
          A(I) = B(I)
3
       CONTINUE
     END IF
     GO TO 30
     END
     SUBROUTINE SYNDIV (A, N, P1, P2, B, R, Q)
   ______
     IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
  Given a polynomial: a(n)*x**n + ...+a(1)*x +a(0)
*
  and a quadratic: x**2 + p1*x + p2
  calculate the coefficients of the quotient polynomial: b(k), k=0,1,\ldots,n-2
  and the remainder terms r and q.
*
     DIMENSION A(0:*), B(0:*)
     B(N-2) = A(N)
     B(N-3) = A(N-1)-P1*B(N-2)
     DO 1 K=N-2,2,-1
        B(K-2) = A(K)-P1*B(K-1)-P2*B(K)
1
     CONTINUe
     R = A(1) - P1*B(0)-P2*B(1)
     Q = A(0) - P2*B(0)
     END
     SUBROUTINE SYNDER (A, N, P1, P2, B, R, Q, B1, B2, R1, R2, Q1, Q2)
```

```
IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
  Given a polynomial: a(n)*x**n + ...+a(1)*x +a(0)
  and a quadratic: x**2 + p1*x + p2
* calculate the coefficients of the quotient polynomial: b(k), k=0,1,\ldots,n-2
  and the remainder terms r and q.
 Calculate the derivatives: b1(k),r1,q1 of b(k),r and q with respect to p1,
  and the derivatives: b2(k),r2,q2 of b(k),r and q with respect to p2.
     DIMENSION A(0:*), B(0:*), B1(0:*), B2(0:*)
     B(N-2) = A(N)
     B(N-3) = A(N-1) - P1*B(N-2)
     DO 1 K=N-2,2,-1
        B(K-2) = A(K) - P1*B(K-1) - P2*B(K)
1
     CONTINUE
     R = A(1) - P1*B(0)-P2*B(1)
     Q = A(0) - P2*B(0)
     B1(N-2) = 0
     B1(N-3) = -A(N)
     D0 2 K=N-2,2,-1
        B1(K-2) = -B(K-1) - P1*B1(K-1) - P2*B1(K)
2
     R1 = -B(0) - P1*B1(0) - P2*B1(1)
     Q1 = -P2*B1(0)
     B2(N-2) = 0
     B2(N-3) = 0
     DO 3 K=N-2,2,-1
        B2(K-2) = -P1*B2(K-1) - B(K) - P2*B2(K)
3
     CONTINUE
     R2 = -P1*B2(0) - B(1) - P2*B2(1)
     Q2 = -B(0) - P2*B2(0)
     END
     _____
     SUBROUTINE SUBSUM ( M, N, X, F )
     IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
     DIMENSION X(N), F(M)
     COMMON /TOROOT/ A(0:100), B(0:100), KCO
     P1 = X(1)
     P2 = X(2)
```

```
CALL SYNDIV (A, KCO, P1, P2, B, R, Q)
      F(1) = R
      F(2) = Q
      END
      SUBROUTINE GRANAL ( N, X, GRAD )
  _____
      IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
      DIMENSION X(N), GRAD(N)
      COMMON /TOROOT/ A(0:100), B(0:100), KCO
      DIMENSION B1(0:100), B2(0:100)
      P1 = X(1)
      P2 = X(2)
      CALL SYNDER (A, KCO, P1, P2, B, R, Q, B1, B2, R1, R2, Q1, Q2)
      GRAD(1) = 2*(R*R1 + Q*Q1)
      GRAD(2) = 2*(R*R2 + Q*Q2)
      END
      SUBROUTINE JANAL ( M, N, X, FJ, LD )
      IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
      DIMENSION X(N), FJ(LD,N)
      COMMON /TOROOT/ A(0:100), B(0:100), KCO
      DIMENSION B1(0:100), B2(0:100)
      P1 = X(1)
      P2 = X(2)
      CALL SYNDER (A, KCO, P1, P2, B, R, Q, B1, B2, R1, R2, Q1, Q2)
      FJ(1,1) = R1
      FJ(1,2) = R2
      FJ(2,1) = Q1
      FJ(2,2) = Q2
      END
We list the Input/Output of a run for obtaining the roots of the polynomial: x^6 - 4x^5 +
2x^4 + 8x^3 - 7x^2 - 4x + 4 which is an expansion of: (x+1)^2(x-1)^2(x-2)^2
Enter a termination tolerance:
1.e-12
Enter the degree of the polynomial:
Enter the polynomial coefficients: (a(0), a(1), ...)
   -4. -7. 8. 2. -4. 1.
_____
```

Running with the following input

```
Tolerance: 1.E-12
Degree:
       Coefficients a(i), i=0,1,...
 4. -4. -7. 8. 2. -4. 1.
_____
 The roots of the polynomial are:
         1 ( 1.000000
 root #
                             0.000000
 root #
       2 ( -1.000000
                             0.000000
                                       )
 root # 3 ( 1.000000
                            0.000000
                                       )
 root # 4 (-1.000000 , 0.000000 root # 5 (2.000000 , 0.000000
                                       )
                                       )
 root # 6 ( 2.000000 ,
                            0.000000
                                       )
```

The input instructions to OPTIMA that reside in the file in.dat are as:

ANAL
JANAL
LEVE NOC 1000
TOLMIN NOC 1000

4.2 Sample code for multistart

```
PROGRAM MSTART
* Sample code for multistart.
 Illustrates the use of subroutine optima.
      IMPLICIT DOUBLE PRECISION (A-H, 0-Z)
      PARAMETER ( N = 2, M = 0 )
      DIMENSION XP(N), XLL(N), XRL(N), IXAT(N), ICODE(4)
      CHARACTER*10 FINP, FOUT
* The input Merlin-instructions reside in file: in.dat
 Merlin's output will be disposed to: /dev/null (Trash file)
      DATA FINP / 'in.dat' /
      DATA FOUT / '/dev/null' /
 Instruct Merlin to initialize the parameters from array XP,
  and to ignore the input for lower bounds, upper bounds and fix-status.
      DATA ICODE / 1, 0, 0, 0 /
      D0 2 J=1,10
* Fill the XP array with random numbers in the range (-7,7)
* Routine RANM() is provided by Merlin.
```

```
DO 1 I=1, N
             XP(I) = 7*(2*RANM()-1)
          CONTINUE
1
  Perform local optimization.
          CALL OPTIMA (N, M, XP, XV, XLL, XRL, IXAT, ICODE,
                       FINP, FOUT, GRMS, NF, NG, NH, NJ)
     &
          IF (J.EQ.1) WRITE (*,70)
          WRITE (*,71) J, NF, NG, XV, (XP(I),I=1,N), GRMS
2
      CONTINUE
      FORMAT (3X, 'J', 4x, 'FE', 4X, 'GE', 7X, 'VAL', 11X, '. . . . XP . . . . ',
70
     &
                10x, 'GRMS')
      FORMAT (1X, I3, 1x, I5, 1X, I5, 2X, D12.5, 1X, 10(2X, D12.5))
71
      END
```

The produced output is displayed below:

J	FE	GE	VAL	X	Р	GRMS
1	47	13	-0.10316E+01	0.89842E-01	-0.71266E+00	0.89234E-08
2	28	19	-0.21546E+00	-0.17036E+01	0.79608E+00	0.49642E-08
3	13	10	-0.10316E+01	0.89842E-01	-0.71266E+00	0.81464E-09
4	22	17	-0.10316E+01	-0.89842E-01	0.71266E+00	0.34503E-12
5	32	24	-0.10316E+01	-0.89842E-01	0.71266E+00	0.43907E-07
6	26	18	-0.21546E+00	0.17036E+01	-0.79608E+00	0.36890E-07
7	33	19	-0.10316E+01	-0.89842E-01	0.71266E+00	0.36883E-07
8	37	25	0.21043E+01	0.16071E+01	0.56865E+00	0.23094E-07
9	28	21	0.21043E+01	-0.16071E+01	-0.56865E+00	0.27245E-08
10	13	12	-0.10316E+01	-0.89842E-01	0.71266E+00	0.24530E-07

The file: in.dat that contains the Merlin instructions and specifies the method(s) used for the local search is displayed below.

```
ANAL
DFP NOC 2000
```

The above is produced with the DFP method (Davidon, Fletcher, Powell). To change the minimization method to another, say to the BFGS method, edit the in.dat file and change the second line to:

BFGS NOC 2000

4.3 Molecular conformation problem

The geometrical structure is an important property for understanding and predicting the behavior of any molecular system. It is the necessary starting point for the derivation of structural features, the estimation of steric requirements, and the calculation of electronic properties. For systems with many degrees of freedom, the potential energy hypersurface may have a substantial number of local minima that correspond to stable molecular configurations. Triglycerides are important biological compounds. Among other functions they serve as structural components of the cell membranes and as a source of carbon atoms for biosynthetic reactions. Glycerol triacetate also known as triacetin is a highly flexible molecule, hence its properties do not depend only on the globally optimal conformational state.

Triacetin consists of 29 atoms which form three branches named α , β and γ as shown in fig. 1. The 15 heavy atoms form a backbone structure with 8 rotational degrees of freedom, while the rotation of the terminal methyl groups add 3 more. For the potential function we used the MM2 [3] force field with 1991 parameters, as implemented in the Tinker [4] molecular modeling package. Triacetin was modelled using internal coordinates. Bond lengths and angles were fixed to their equilibrium values while the 11 dihedral angles were allowed to vary. We applied the parallel TML algorithm using 4 processors on a SUN Enterprise 450, with the following default parameter values:

```
ITTHR=10 HEAL=5 NEARN=2 NSAMPL=100 SIGMA=4 COVTHR=0.995 XDEPS=1.e-2 FDEPS=1.e-4 GDEPS=1.e-5
```

For the local optimization we used the TOLMIN method with a maximum of 5000 function calls. The TML algorithm performed 29780 iterations, 3982011 function and 993272 gradient calls. A total of 2181 local minima were found. After TML completed all minima were further refined using the full set of internal coordinates. Using this procedure we recovered all 109 low energy conformers described in [5]. The global minimum is shown in fig. 2, while the next lowest is shown in fig. 3.

5 Using MCL with the OPTIMA interface

We present a general strategy, coded in MCL, and then show how it can be used with the OPTIMA interface.

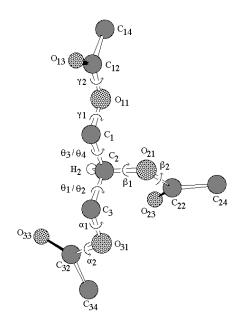


Figure 1: The triacetin molecule

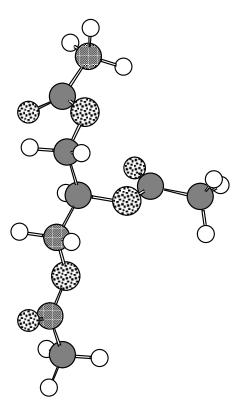


Figure 2: Lowest energy conformer of triacetin

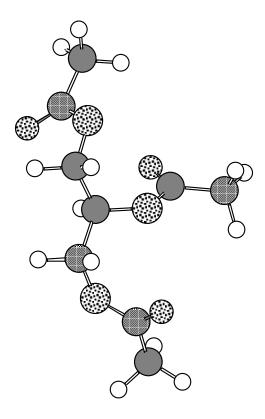


Figure 3: The second lowest energy triacetin conformer

```
% GEPS is input and is a tolerance for the rms gradient.
\% NOCALLS is input and adjusts the number of calls to the objective
          function.
% Care is taken to use proper methods depending on the existance
\% of analytic derivatives, jacobian and the functional form.
   var ic;z
   ic = 0
REDO:
   if funmode == 0 then
                                  % General form (FUNCTION FUNMIN)
      if deriva == 1 then
                                  % Analytic gradient exists.
         tolmin(NOC=nocalls)
         when grms[z] > geps just simplex(NOC=nocalls)
%
      else
                                  % Analytic gradient does not exist
         simplex(NOC=nocalls)
         when grms[z] > geps just bfgs(NOC=nocalls)
      endif
                                  % Sum of Squares form (SUBSUM)
   else
      if jacomo == 1 then
                                  % Analytic Jacobian exists
```

Compile the above MCL program and let the object code be the input file (FINP) to subroutine optima.

References

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- [4] J. W. Ponder, TINKER 3.7 of June 1999, Availability: http://dasher.wustl.edu/tinker/
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