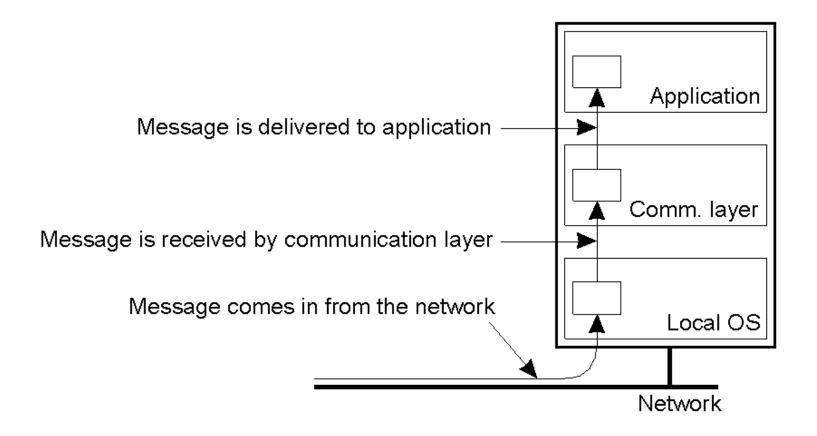
MYE017 Distributed Systems

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Message reception vs. delivery



The logical organization of a distributed system to distinguish between message receipt and message delivery

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FIFO message ordering

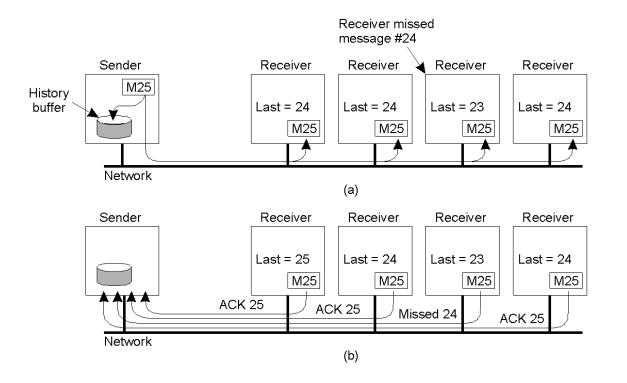
Process P1	Process P2	Process P3	Process P4
sends m1	delivers m1	delivers m3	sends m3
sends m2	delivers m3	delivers m1	sends m4
	delivers m2	delivers m2	
	delivers m4	delivers m4	

- Four processes in a group with two different senders
- A possible delivery order under FIFO multicasting

Versions of multicasting

Multicast	Basic Message Ordering	Total-ordered Delivery?
Reliable multicast	None	No
FIFO multicast	FIFO-ordered delivery	No
Causal multicast	Causal-ordered delivery	No
Atomic multicast	None	Yes
FIFO atomic multicast	FIFO-ordered delivery	Yes
Causal atomic multicast	Causal-ordered delivery	Yes

Reliable multicasting, basic schemes

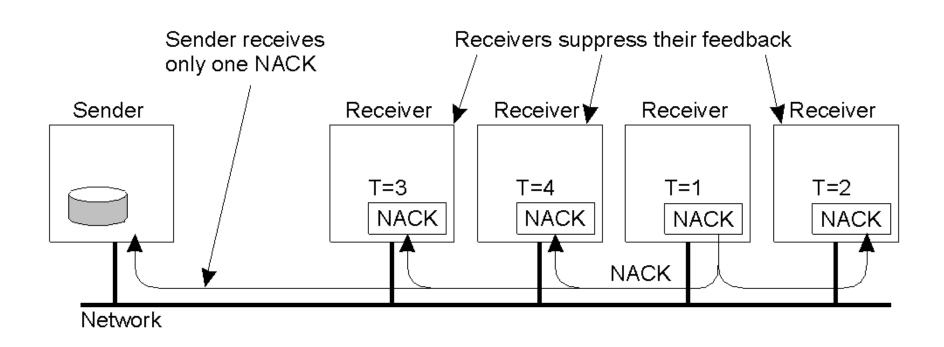


A simple solution to reliable multicasting when all receivers are known and assumed not to fail

- a) Message transmission
- b) Reporting feedback

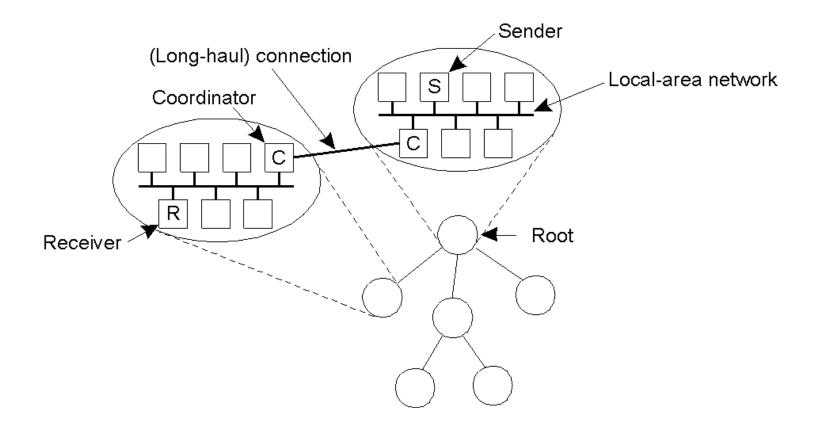
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Nonhierarchical feedback control



Several receivers have scheduled a request for retransmission, but the first retransmission request leads to the suppression of others

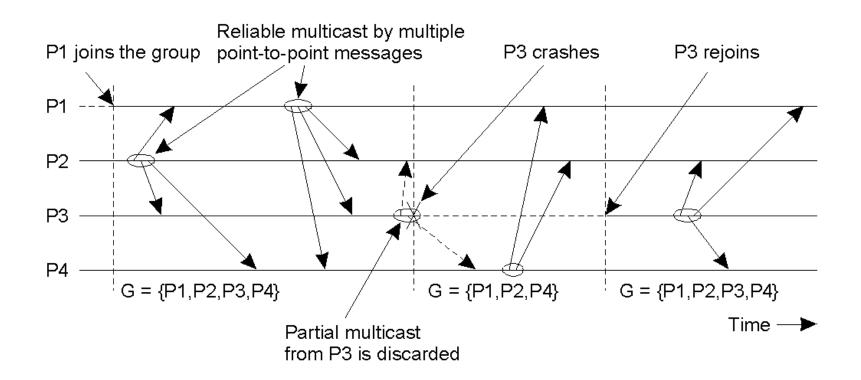
Hierarchical feedback control



The essence of hierarchical reliable multicasting

- a) Each local coordinator forwards the message to its children
- b) A local coordinator handles retransmission requests

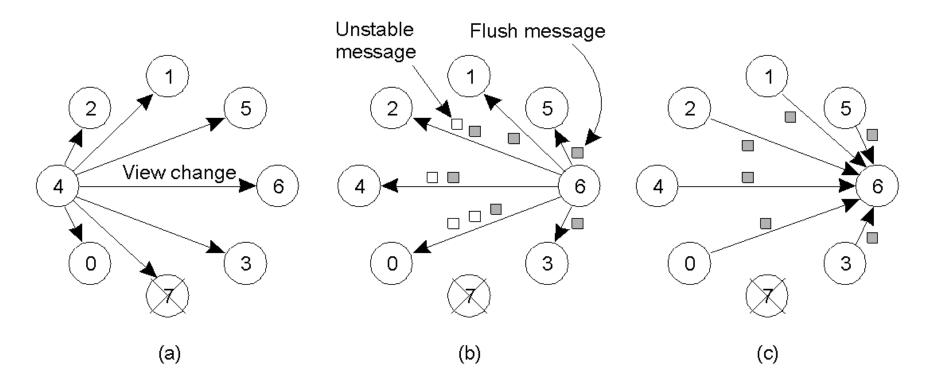
Virtual Synchrony



The principle of virtual synchronous multicast

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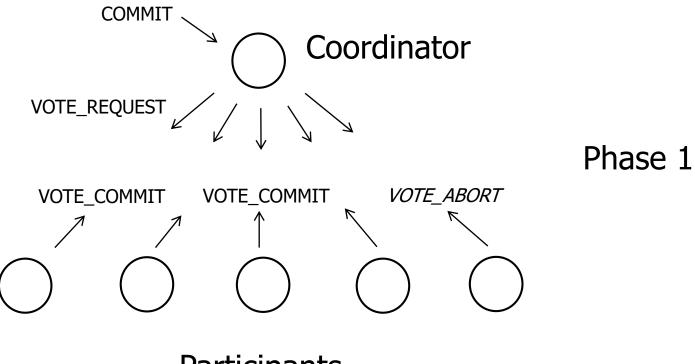
Implementing Virtual Synchrony (2)



- Process 4 notices that process 7 has crashed, sends a view change
- Process 6 sends out all its unstable messages, followed by a flush message
- Process 6 installs the new view when it has received a flush message from everyone else

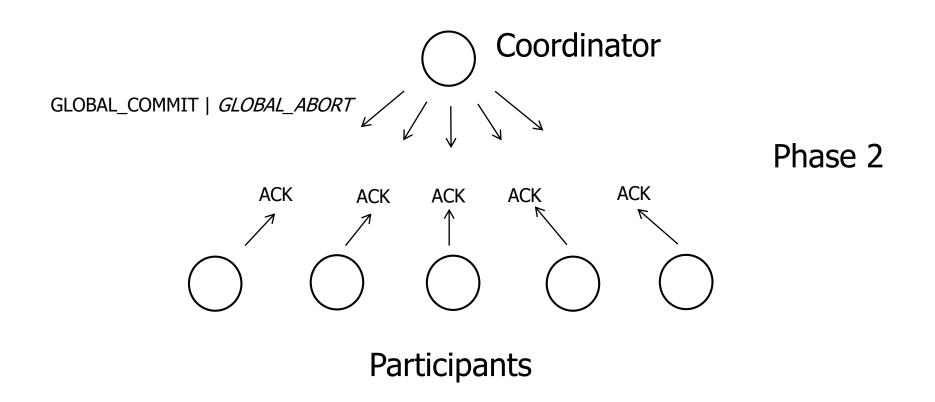
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Two-phase commit

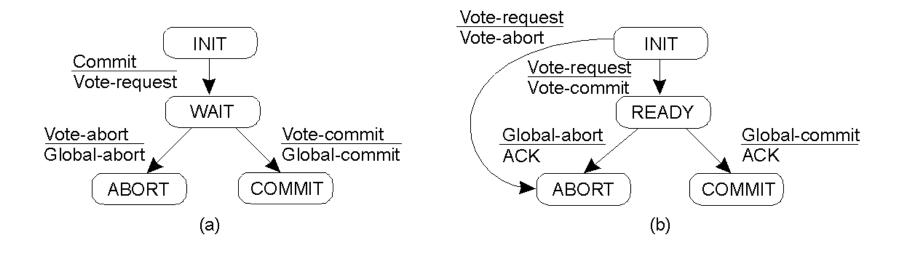


Participants

Two-phase commit

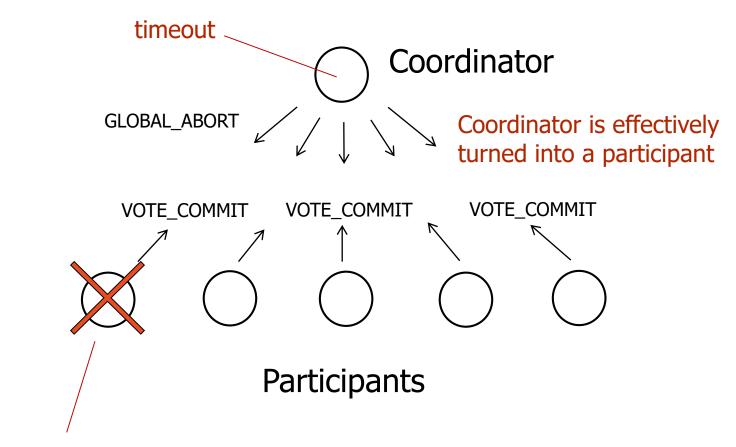


2PC - State machines



a) The finite state machine for the coordinator in 2PCb) The finite state machine for a participant

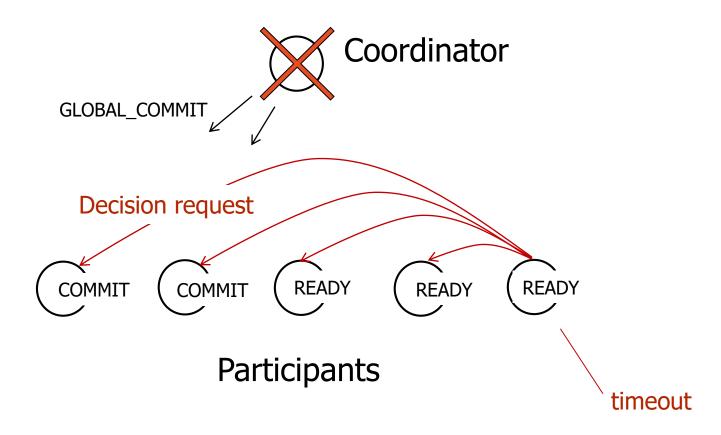
2PC – Operation under failures



A participant crashes, disconnects, or is too slow during a vote

2PC – Operation under failures

Coordinator crashes after sending a few (but not all) commit messages



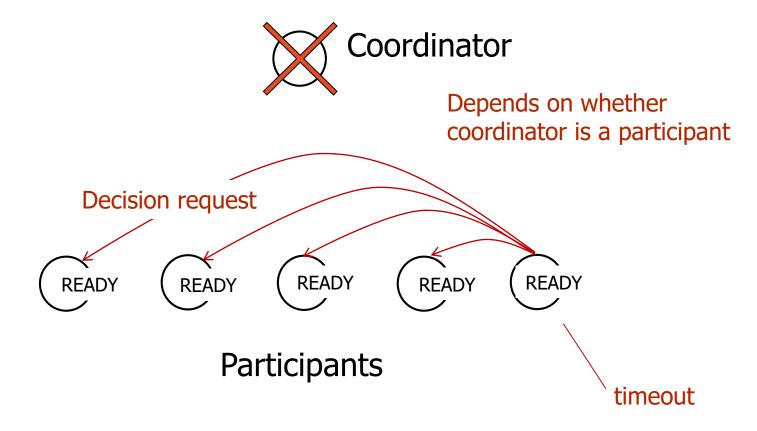
2PC – Coordinator crash

State of Q	Action by P
COMMIT	Make transition to COMMIT
ABORT	Make transition to ABORT
INIT	Make transition to ABORT
READY	Contact another participant

Actions taken by a participant P when residing in state *READY* and having contacted another participant Q.

2PC – What happens if all in READY state?

Coordinator crashes, disconnects, or is too slow



2PC – May block forever

Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant

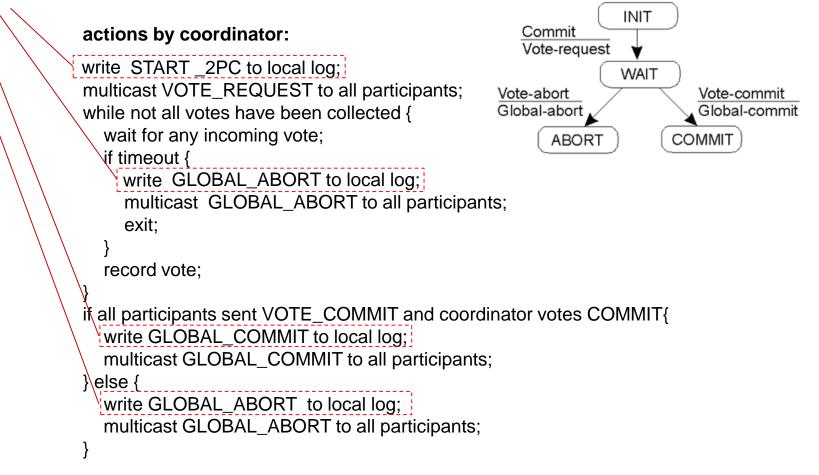


Crashed participant may be the only one that knows decision



2PC – Actions by coordinator

Ensure that state is recoverable



2PC – Actions by participant

actions by participant:

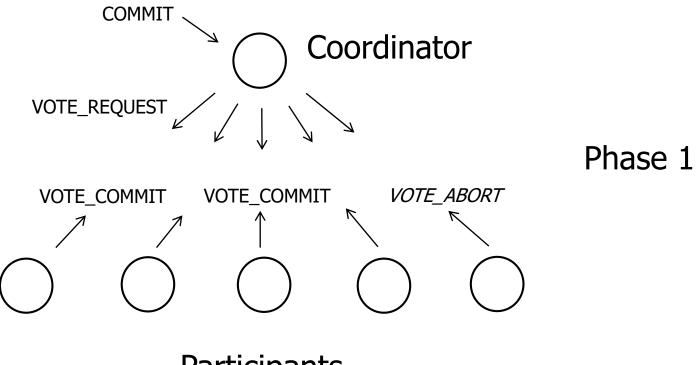
```
write INIT to local log;
wait for VOTE_REQUEST from coordinator;
if timeout {
                                                    Vote-request
  write VOTE_ABORT to local log;
                                                    Vote-abort
                                                                      INIT
  exit:
                                                           Vote-request
                                                           Vote-commit
                                                                      ۷
if participant votes COMMIT {
                                                                    READY
                                                        Global-abort
                                                                               Global-commit
  write VOTE_COMMIT to local log;
                                                        ACK
                                                                               ACK
  send VOTE COMMIT to coordinator;
                                                             ABORT
                                                                           COMMIT
  wait for DECISION from coordinator;
  if timeout {
     multicast DECISION_REQUEST to other participants;
    wait until DECISION is received; /* remain blocked */
    write DECISION to local log;
  if DECISION == GLOBAL COMMIT
    write GLOBAL_COMMIT to local log;
  else if DECISION == GLOBAL ABORT
    write GLOBAL_ABORT to local log;
} else {
  write VOTE ABORT to local log
  send VOTE ABORT to coordinator;
```

2PC – Handling incoming decision requests

actions for handling decision requests: /* executed by separate thread */

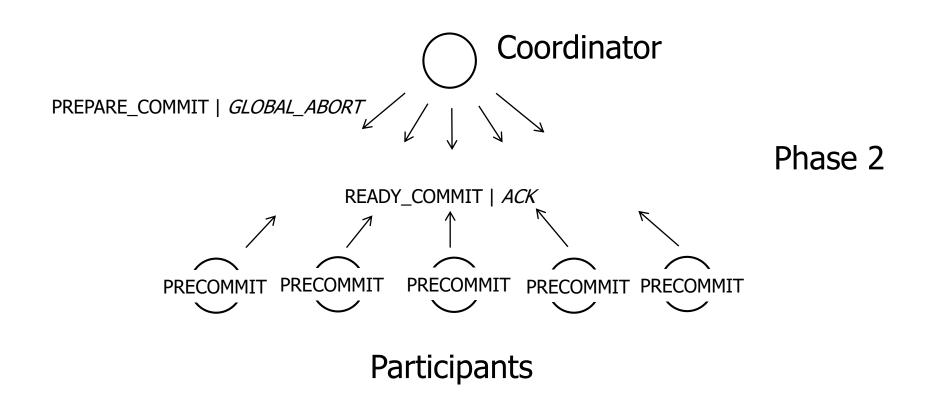
```
while true {
    wait until any incoming DECISION_REQUEST is received; /* remain blocked */
    read most recently recorded STATE from the local log;
    if STATE == GLOBAL_COMMIT
        send GLOBAL_COMMIT to requesting participant;
    else if STATE == INIT or STATE == GLOBAL_ABORT
        send GLOBAL_ABORT to requesting participant;
    else
        skip; /* participant remains blocked */
```

Three-phase commit

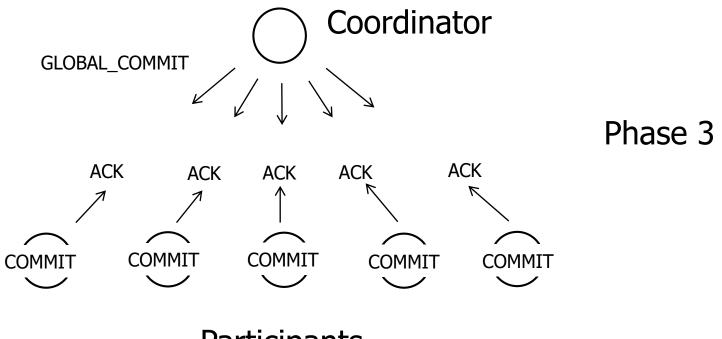


Participants

Three-phase commit

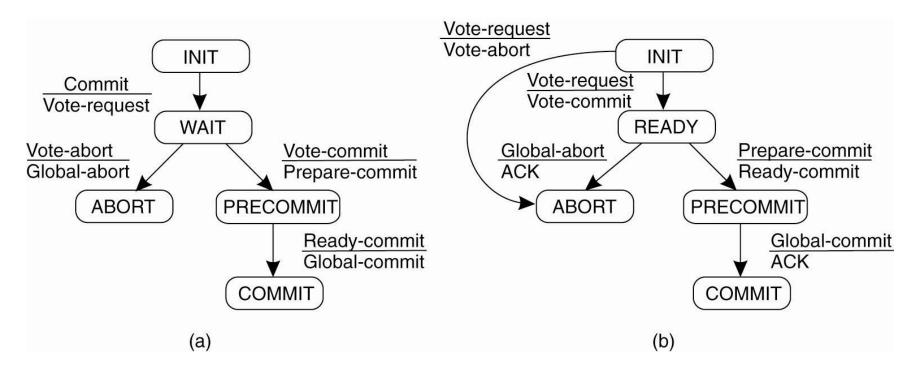


Three-phase commit



Participants

Three-phase commit (2)



(a) The finite state machine for the coordinator in 3PC(b) The finite state machine for a participant

Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant



Crashed participant may not have voted abort or aborted, thus <u>can commit</u>



Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant



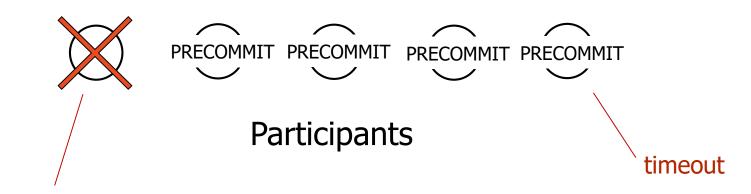
Coordinator cannot have issued a commit, thus they can abort



Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant



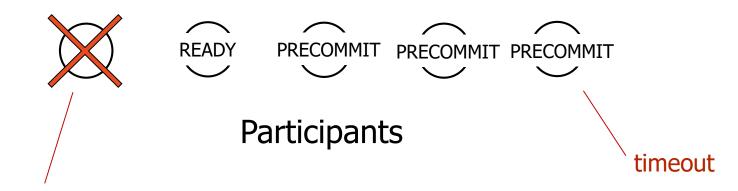
Crashed participant may not have voted abort or aborted, thus <u>can commit</u>



Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant

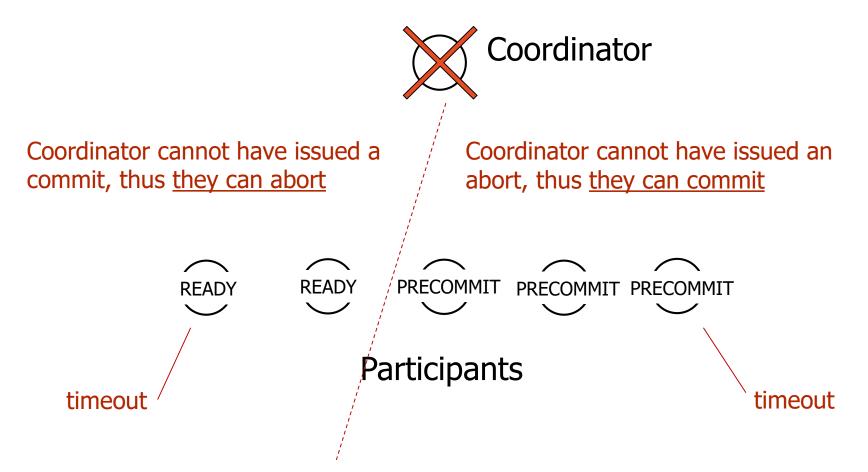


Coordinator cannot have issued an abort, thus <u>can commit</u>

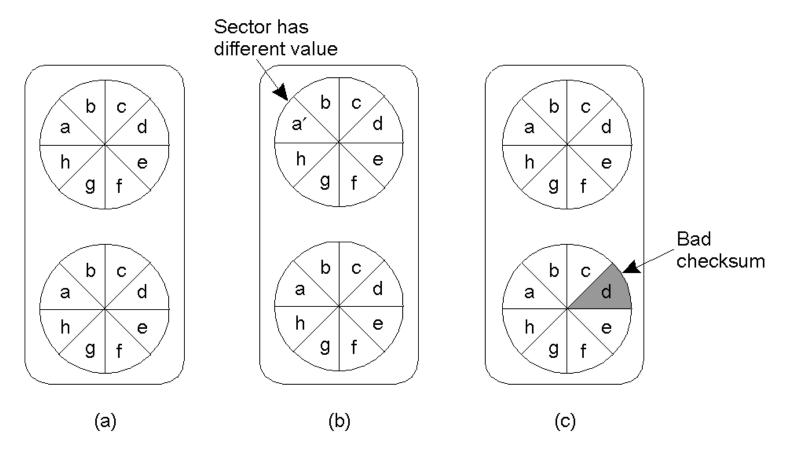


3PC – partitions are problematic

Coordinator crashes, disconnects, or is too slow – but <u>not</u> a participant

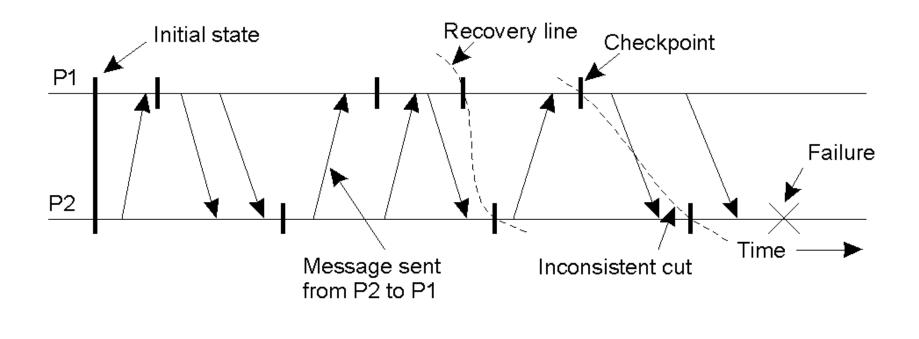


Recovery Stable Storage



a) Stable Storageb) Crash after drive 1 is updatedc) Bad spot

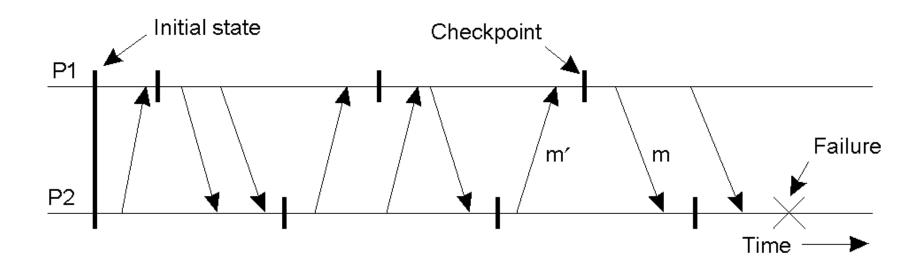
Checkpointing



A recovery line

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Independent Checkpointing



The domino effect

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