Streaming Model of Computation

A streaming algorithm processes a data stream *S*:

- Input is presented as a sequence of items and can be examined in only a few passes (typically just one).
- The algorithm has limited memory and cannot store the whole input sequence.
- The algorithm can spend limited processing time per item.
- In some problems we are satisfied with an approximate answer.
- Approximation algorithms can be based on sketches (summaries) of the data stream in memory.

In many applications we deal with massive graphs. E.g. (vertices – edges):

- Web-pages hyperlinks
- Neurons synapses
- IP addresses network flows
- People friendships

Processing such graphs with a classic graph algorithm may be infeasible!

But it may be possible to use an algorithm developed for the data stream model.

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Processing such graphs with a classic graph algorithm may be infeasible!

But it may be possible to use an algorithm developed for the data stream model.

Presentation based on: A. McGregor "Graph Stream Algorithms: A Survey" [ACM SIGMOD Record 2014]

The Internet

Graph from Albert-László Barabási' s SIGIR09 keynote

Data stream model

- The input is given by a stream of data. E.g., the stream could be the graph edges.
- The algorithm can use a limited amount of memory to process the stream.
- The input stream must be processed in the order it arrives.

Related goals:

- Real-time systems.
- I/O efficiency.
- Trade-off size and accuracy.

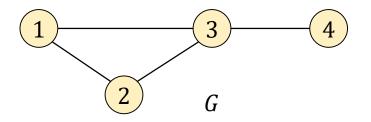
Data stream model

How much memory should our model allow in order to be able to process a graph with n vertices?

- Most problems are intractable if space is < n.
- We will work in the semi-streaming model that allows O(n log^kn) memory, for some constant k.
- Some algorithms will be randomized. We will say that an event *E* occurs with high probability if $Pr[E] \ge 1 1/n$.

Graph connectivity

Data stream S: Edges of a graph G = (V, E) with n = |V|

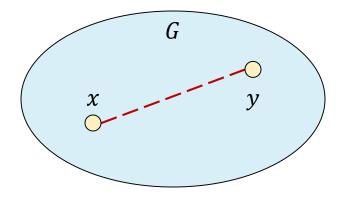


E.g., data stream S = (1,2), (2,3), (1,3), (3,4)

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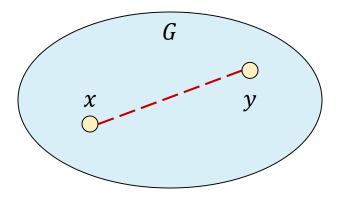
The goal is to test if G is connected, i.e., for any two vertices there is a path that connects them.



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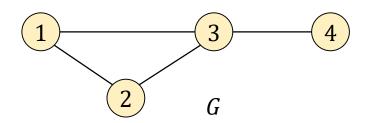
Simple algorithm: Maintain a set of edges *H*. When we read the next edge (u, v) from the stream, we add it to *H* if there is currently no path between *u* and *v*.

Spanners

a-spanner H of a graph G = (V, E): subgraph of G such that for all pairs $u, v \in V$,

$$d_G(u,v) \le d_H(u,v) \le a \cdot d_G(u,v)$$

 $d_G(u, v) =$ length of the shortest path between u and v in G $d_H(u, v) =$ length of the shortest path between u and v in H



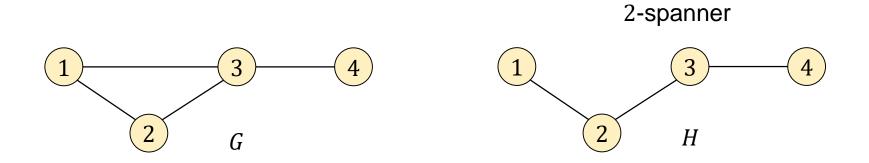
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Spanners

Construction of an *a*-spanner *H*: add next edge (u, v) if it does not create a short cycle in *H*

Greedy Spanner Algorithm

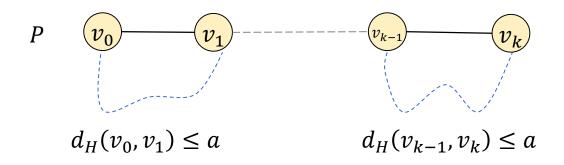
- 1. $H \leftarrow \emptyset$
- 2. for each edge $(u, v) \in S$ do
- 3. **if** $d_H(u, v) > a$ **then** add (u, v) to H
- 4. return *H*
- Does this work?
- What is the size (#edges) of the spanner?

Spanners

Proof that the Greedy Spanner Algorithm works:

For any edge (x, y) of *G* we have $d_H(x, y) \le a$.

Consider a path $P = (v_0, v_1, \dots, v_{k-1}, v_k)$ in G



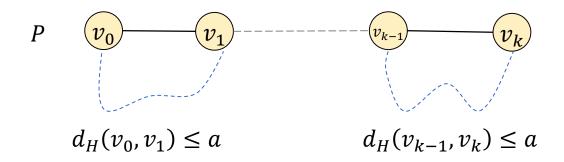
Length of *P* in $G = k = d_G(v_0, v_1) + d_G(v_1, v_2) + \dots + d_G(v_{k-1}, v_k)$

Spanners

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Length of *P* in $G = k = d_G(v_0, v_1) + d_G(v_1, v_2) + \dots + d_G(v_{k-1}, v_k)$

Length in $H \leq d_H(v_0, v_1) + d_H(v_1, v_2) + \dots + d_H(v_{k-1}, v_k)$ $\leq a \cdot d_G(v_0, v_1) + a \cdot d_G(v_1, v_2) + \dots + a \cdot d_G(v_{k-1}, v_k) = a \cdot k$

Spanners

How many edges are inserted into *H*?

- Let a = 2t 1, for some integer *t*.
- Then *H* does not contain cycles of length < 2t.
- By a known result in Graph Theory, any such graph has at most

$$0(n^{1+1/t})$$

edges.

Minimum Spanning Tree

Data stream S: Edges of a weighted graph G = (V, E, w) with n = |V|

Construction: if next edge (u, v) creates a cycle *C* in *H*, delete from *H* the maximum weight edge of *C*.

Greedy MST Algorithm

- 1. $H \leftarrow \emptyset$
- 2. for each edge $e = (u, v) \in S$ do
- 3. **if** *e* creates a cycle *C* in *H* **then**
- 4. find the maximum weight edge $f \in C$
- 5. add *e* to *H*
- 6. delete *f* from *H*
- 7. return *H*

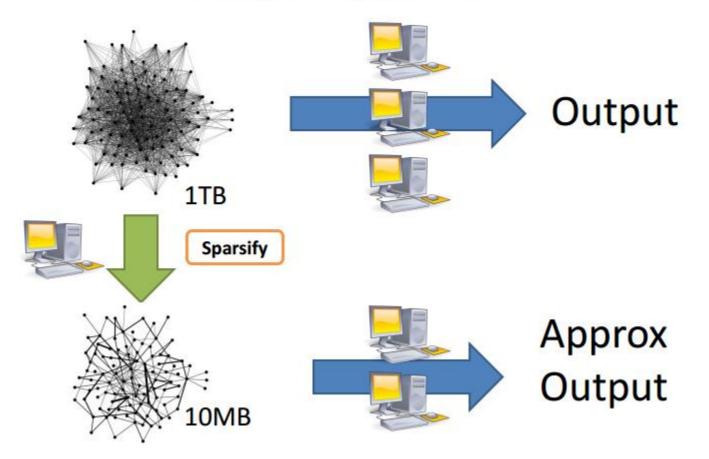
Graph Sparsification

Given a graph G = (V, E) we want to construct a **weighted subgraph** $H = (V, E_H, w)$ of *G* that estimates various (connectivity) properties of *G*

E.g.:

- Cut sparsification [Benczur-Karger]
- Spectral sparsification [Spielman-Teng]

Sample Application



Picture from https://simons.berkeley.edu/sites/default/files/docs/1768/slidessrivastava1.pdf

Cuts in Graphs

Weighted graph G = (V, E, w). Edge weights $w : E \to R$

A-cut: partition of V into two sets A and $V \setminus A$

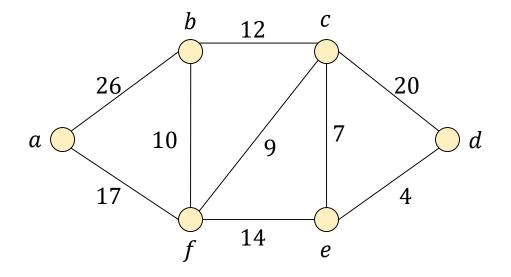
 $\delta_G(A) = \text{set of edges in } G \text{ crossing the } A \text{-cut. } \delta_G(A) = \{(u, v) \in E : u \in A, v \in V \setminus A\}$

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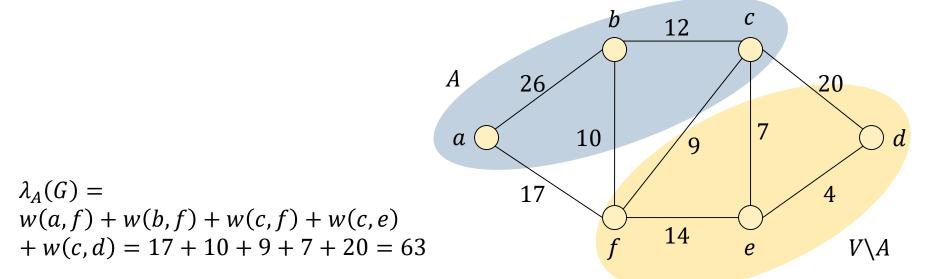


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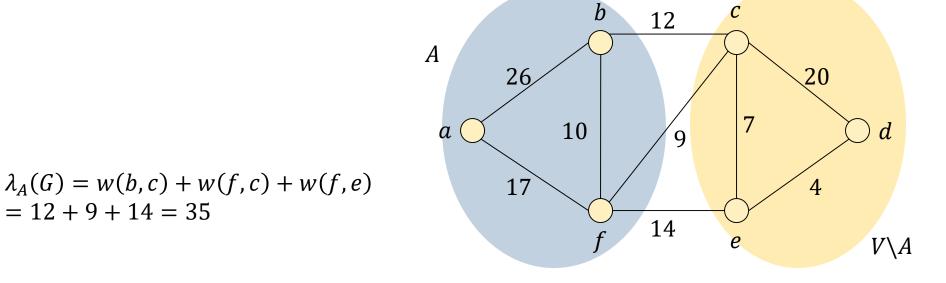
Cuts in Graphs

= 12 + 9 + 14 = 35

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Cut Sparsification

Given a graph G = (V, E) we want to construct a **weighted subgraph** $H = (V, E_H, w)$ of *G* that estimates the size of each cut of *G*

 $(1 + \varepsilon)$ cut sparsification

$$(1-\varepsilon)\cdot\lambda_A(G) \leq \lambda_A(H) \leq (1+\varepsilon)\cdot\lambda_A(G)$$

for all vertex subsets $A \subset V$

Graph Laplacian

Weighted graph G = (V, E, w). Edge weights $w : E \to R$

Laplacian of $G: n \times n$ real matrix $L_G, n = |V|$

$$L_G(i,j) = \begin{cases} \sum_{(i,k)\in E} w(i,k), & i=j \\ -w(i,j), & i\neq j \end{cases}$$

where w(i, j) = 0 if $(i, j) \notin E$

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Let
$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$
 be a real vector in \mathbb{R}^n . Recall that $x^T = (x_1 \quad \cdots \quad x_n)$

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Then

$$x^{T}L_{G}x = \sum_{(i,j)\in E} w(i,j)(x_{i}-x_{j})^{2}$$

Spectral Sparsification

Graph G = (V, E)

A weighted subgraph $H = (V, E_H, w)$ of G is a $(1 + \varepsilon)$ spectral sparsifier of G if

$$(1 - \varepsilon) \cdot x^T L_G x \leq x^T L_H x \leq (1 + \varepsilon) \cdot x^T L_G x$$

for all real vectors $x \in \mathbb{R}^n$

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A spectral sparsifier of *G* can approximate:

- Size of all cuts
- Eigenvalues
- Effective resistances (in the corresponding electrical network)
- Properties of random walks

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Theorem [Spielman and Teng] A $(1 + \varepsilon)$ spectral sparsifier with $O(n \log n / \varepsilon^2)$ edges can be constructed in $O(m \operatorname{polylog}(n) / \varepsilon^2)$, where *n* is the number of vertices and *m* is the number of edges of the input graph.

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Theorem [Batson, Spielman and Srivastava] A graph with *n* vertices has a $(1 + \varepsilon)$ spectral sparsifier with $O(n/\varepsilon^2)$ edges.

Spectral Sparsification – Construction in the semi-streaming model

- Use as a black box any existing algorithm ALG that returns a $(1 + \gamma)$ spectral sparsifier.
- ALG returns a spectral sparsifier with $size(\gamma) = O(n/\gamma^2)$ number of edges.

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We use the following properties of spectral sparsification

- **Mergeable:** Suppose H_1 and H_2 are β spectral sparsifiers of two graphs G_1 and G_2 on the same set of vertices. Then $H_1 \cup H_2$ is a β spectral sparsifier of $G_1 \cup G_2$.
- **Composable:** If H_3 is a β spectral sparsifier for H_2 and H_2 is a δ spectral sparsifier for H_1 then H_3 is a $\beta\delta$ spectral sparsifier for H_1 .

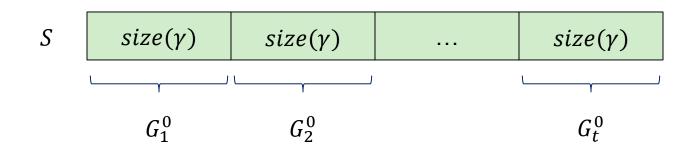
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Let G = (V, E) be the input graph with n = |V| and m = |E|Data stream S = the m edges of G

Set $t = m/size(\gamma)$. For simplicity assume that t is a power of 2

We divide *S* into *t* segments of $size(\gamma)$ edges

 G_i^0 = graph that consists of the edges in the *i*-th segment



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For
$$i = 1, 2, ..., \lg t$$
 and $j = 1, 2, ..., t/2^i$ define $G_i^j = G_{2i-1}^{j-1} \cup G_{2i}^{j-1}$

E.g., f

for
$$t = 4$$

 G_1^0
 G_2^0
 G_3^0
 G_4^0
 G_4^0
 $G_1^1 = G_1^0 \cup G_2^0$
 $G_2^1 = G_3^0 \cup G_4^0$
 $G_1^2 = G_1^1 \cup G_2^1 = G$

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- $H_i^0 = G_i^0$
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Set $\gamma = \varepsilon/(2 \lg t) \Rightarrow (1 + \gamma)^{\lg t} \sim (1 + \varepsilon)$

Then $H_1^{\lg t}$ is a $(1 + \varepsilon)$ sparsifier of *G*

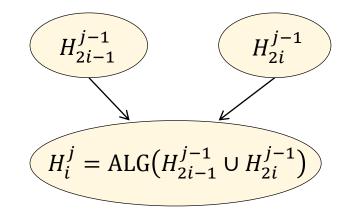
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Space required



Delete H_{2i-1}^{j-1} and H_{2i}^{j-1} as soon as H_i^j is computed \Rightarrow

For each *j* we need to store H_i^j only for two values of *i*

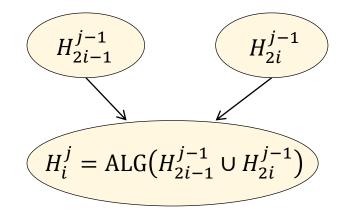
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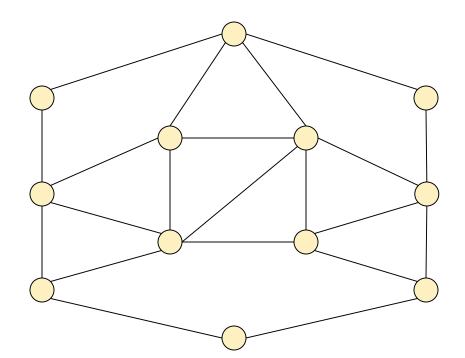
So at any given time we need to store $\leq 2 \cdot size(\gamma) \cdot \lg t = 0(n \lg^3 n/\epsilon^2)$

Matchings

Graph G = (V, E)

Matching: Subset of edges $M \subseteq E$ such that each vertex is adjacent to at most one edge in M

Goal: Find a maximum cardinality matching M^*

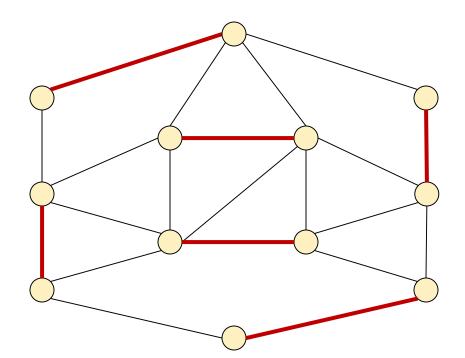


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Greedy Matching Algorithm

- 1. $M \leftarrow \emptyset$
- 2. for each edge $e \in S$ do
- 3. **if** $M \cup \{e\}$ is a matching **then** add *e* to *M*
- 4. return M

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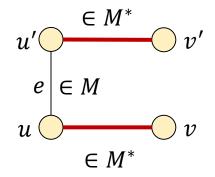
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Consider an edge $(u, v) \in M^*$

If $(u, v) \notin M$ then M must contain at least one edge e adjacent to u or to v

e is adjacent to at most 2 edges of M^*



Weighted Matchings

Weighted graph G = (V, E, w). Edge weights $w : E \to \mathbb{R}^+$ ($w(e) > 0, \forall e \in E$)

Goal: Find a maximum weight matching M^*

As before, we process the edges of the stream S as they arrive and try to augment the current matching M

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Let e be the next edge read from S. Let C be the edges of M that are in conflict with e : and edge in C and e are adjacent to a common vertex.

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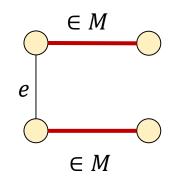
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C has at most two edges. Let w(C) be the total weight of the edges in C.

If w(e) > w(C) then we increase the weight of *M* by including *e* and deleting the edges of *C*.



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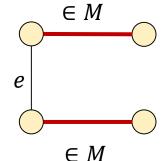
w(C) = total weight of the edges in *C*.

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Greedy Weighted Matching Algorithm

1. $M \leftarrow \emptyset$

- 2. for each edge $e \in S$ do
- 3. let *C* be the set of edges that are in conflict with *e*
- 4. **if** w(e) > w(C) **then** add *e* to *M* and delete *C* from *M*
- 5. return M

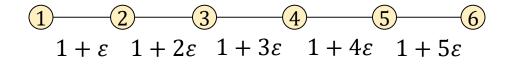


Weighted Matchings

Consider the following scenario

 $S = (1,2), (2,3), (3,4), \dots, (n, n-1)$

Edge $e_i = (i, i + 1)$ has weight $w(e_i) = 1 + i\varepsilon$, for a small $\varepsilon > 0$



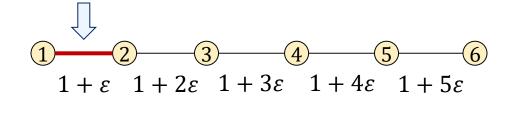
 $M = \{\}$

Weighted Matchings

Consider the following scenario

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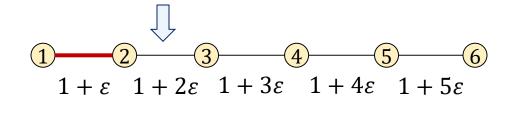
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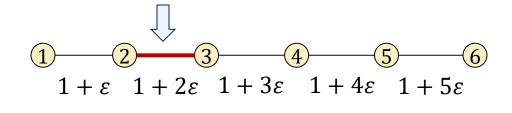
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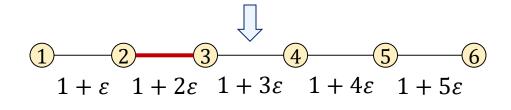
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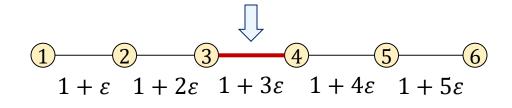
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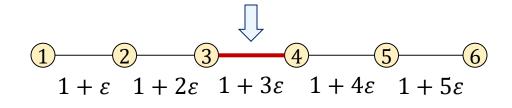
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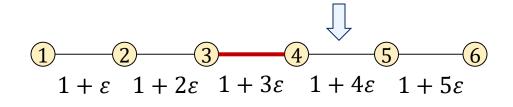
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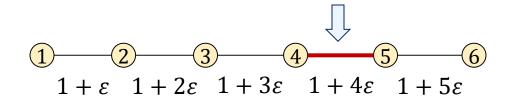
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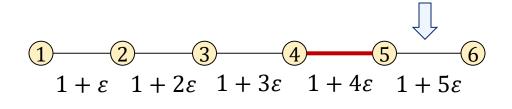
 $M = \{(4,5)\}$

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Consider the following scenario

 $S = (1,2), (2,3), (3,4), \dots, (n, n-1)$

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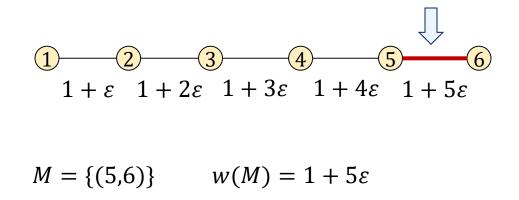
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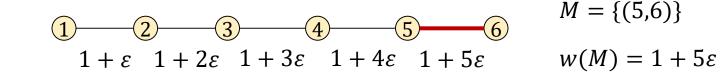


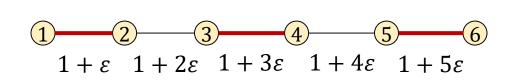
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$$M^* = \{(1,2), (3,4), (5,6)\}$$
$$w(M^*) = 3 + 9\varepsilon$$

Weighted Matchings

Consider the following scenario

$$S = (1,2), (2,3), (3,4), \dots, (n, n-1)$$

Edge $e_i = (i, i + 1)$ has weight $w(e_i) = 1 + i\varepsilon$, for a small $\varepsilon > 0$

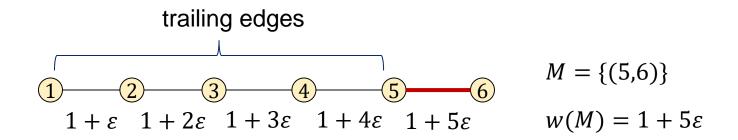
The computed matching *M* has weight $w(M) = 1 + (n - 1)\varepsilon$

The optimal matching *M* has weight $w(M^*) = \sum_i (1 + (2i - 1)\varepsilon) > (n - 1)/2$

Hence, the approximation ratio is

$$\frac{w(M^*)}{w(M)} > \frac{(n-1)/2}{1+(n-1)\varepsilon} \sim \frac{n}{2}$$

Weighted Matchings

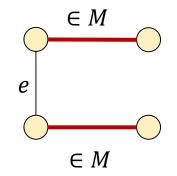


The problem is that the trailing edges of *S* that were once inserted into *M* but removed later may have much larger total weight than the edges added later.

Weighted Matchings

Modified algorithm

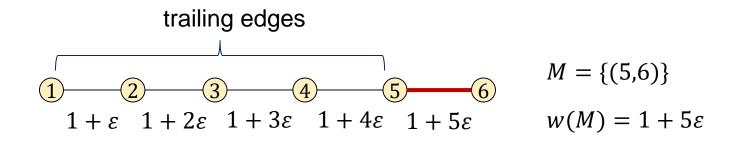
We include *e* in *M* If $w(e) > \beta w(C)$ for some constant $\beta = (1 + \gamma) > 1$.



Greedy Weighted Matching Algorithm

- 1. $M \leftarrow \emptyset$
- 2. for each edge $e \in S$ do
- 3. let *C* be the set of edges that are in conflict with *e*
- 4. **if** $w(e) > (1 + \gamma) \cdot w(C)$ **then** add *e* to *M* and delete *C* from *M*
- 5. return M

Weighted Matchings



The problem is that the trailing edges of S that were once inserted into M but removed later may have much larger total weight than the edges added later.

We include *e* in *M* If $w(e) > \beta w(C)$ for some constant $\beta = (1 + \gamma) > 1$.

For an edge *e* define

- $C_0 = \{e\}$
- C_i = edges removed when an edge in C_{i-1} was added to M
- $T_e = C_1 \cup C_2 \cup \cdots$

Then $w(T_e) \le w(e)/\gamma$

Weighted Matchings

It can be shown that

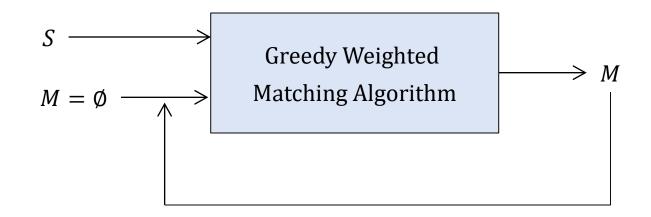
$$w(M^*) \le (1+\gamma) \cdot \sum_{e \in M} (w(T_e) + 2w(e))$$

By applying a careful charging scheme we get

$$\frac{w(M^*)}{w(M)} < 5.828$$

Weighted Matchings

Multi-pass Algorithm

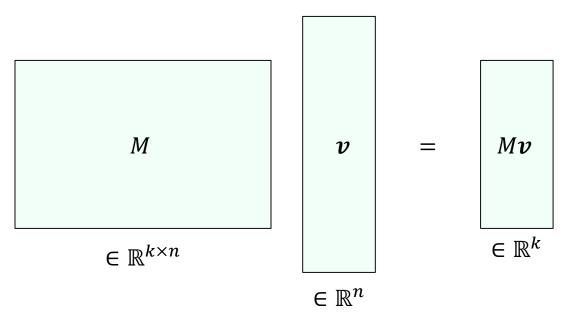


We can get a $(2 + \varepsilon)$ -approximation with $O(\varepsilon^{-3})$ passes over *S*, where $\gamma = O(\varepsilon)$

Graph Sketches

Random linear projection $M : \mathbb{R}^n \to \mathbb{R}^k$, where $k \ll n$

For any vector $v \in \mathbb{R}^n$, the projection $Mv \in \mathbb{R}^k$ preserves properties of v with high probability



Many applications: estimating entropy, heavy hitters, estimating norms, fitting polynomials,...

Rich theory: dimensionality reduction, sparse recovery, metric embeddings,...

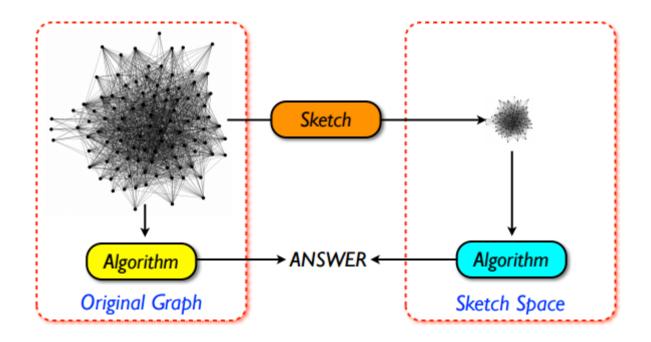
Graph Sketches

Can we use this approach for graphs?

That is, can we project the adjacency matrix A_G of a graph G to a smaller matrix MA_G , so that we can use MA_G to compute properties of G?

- For a graph *G* with n vertices, A_G has $O(n^2)$ dimensions.
- To work in the semi-streaming model we want *MA_G* to have O(*n* polylog(*n*)) dimensions.

Graph Sketches



Picture from https://people.cs.umass.edu/~mcgregor/711S12/lec-2-2.pdf

Graph Sketches

Dynamic graph stream $S = \langle a_1, a_2, ... \rangle$ where $a_i = (e_i, \Delta_i)$

 e_i = an edge of the graph

$$\Delta_i = \begin{cases} +1, e_i \text{ is inserted} \\ -1, e_i \text{ is deleted} \end{cases}$$

Multiplicity of edge e: $f_e = \sum_{i: e_i = e} \Delta_i$

For simplicity we will assume that $f_e \in \{0,1\}$, for all edges e.

Graph Sketches

Vector of edge multiplicities $\mathbf{f} \in \{0,1\}^{\binom{n}{2}}$

Each entry of *f* is a multiplicity f_e of a (potential) edge *e* of *G* (a simple graph with *n* vertices has up to $\binom{n}{2}$ edges).

$$\boldsymbol{f} = \begin{pmatrix} f_{e_{12}} \\ f_{e_{13}} \\ f_{e_{23}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \qquad \begin{array}{c} 1 & e_{13} \\ e_{12} & 2 \\ e_{23} \\ e_{$$

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Index vector of edge $e : i^e \in \{0,1\}^{\binom{n}{2}}$. The only nonzero entry of i^e is the one that corresponds to edge e.

$$\mathbf{i}^{e_{23}} = \begin{pmatrix} i_{e_{12}} \\ i_{e_{13}} \\ i_{e_{23}} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \qquad \begin{array}{c} 1 & e_{13} \\ e_{12} & e_{23} \\ e_{23}$$

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Sketch of $f : A(f) \in \mathbb{R}^d$, d =dimensionality of the sketch

When we read the next item (e, Δ) from the stream, we can update the sketch as follows:

$$A(f) = A(f) + \Delta \cdot A(i^e)$$

Homomorphic Sketches

Vector of edge multiplicities $\mathbf{f} \in \{0,1\}^{\binom{n}{2}}$

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For a vertex $v \text{ let } f^v \in \{0,1\}^{n-1}$ be the restriction of f to the coordinates that involve v (i.e., the n-1 edges that can be adjacent to v in G)

$$f = \begin{pmatrix} f_{e_{12}} \\ f_{e_{13}} \\ f_{e_{23}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$f^{1} = \begin{pmatrix} f_{e_{12}} \\ f_{e_{13}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Homomorphic Sketches

Vector of edge multiplicities $\mathbf{f} \in \{0,1\}^{\binom{n}{2}}$

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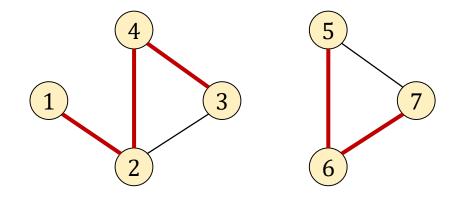
For a vertex v let $f^{v} \in \{0,1\}^{n-1}$ be the restriction of f to the coordinates that involve v (i.e., the n-1 edges that can be adjacent to v in G)

The sketches of f are formed by concatenation (\circ) of the sketches of each f^{ν}

$$A(\boldsymbol{f}) = A_1(f^{v_1}) \circ A_2(f^{v_2}) \circ \cdots \circ A_n(f^{v_n})$$

Homomorphic sketches: For each operation on G there is a corresponding operation on the sketches

Connectivity via Sketches



Connectivity via Sketches

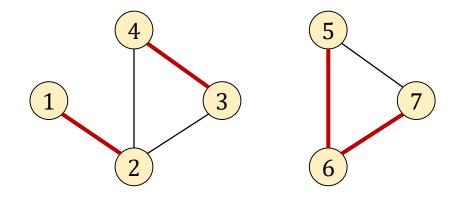
We wish to maintain a spanning forest of a graph G = (V, E)

Let's begin with a simple (non-sketch) algorithm

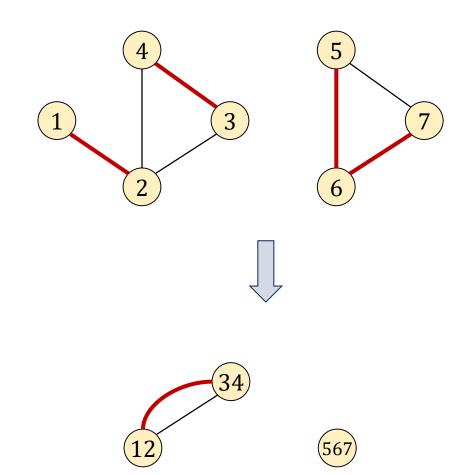
Connectivity Algorithm

- 1. repeat
- 2. **for** each vertex *v* of the current graph **do**
- 3. select an edge incident to v
- 4. contract all selected edges
- 5. **until** the current graph has no edges

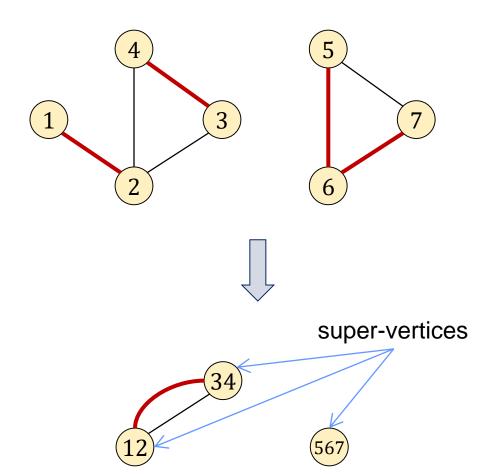
Connectivity via Sketches



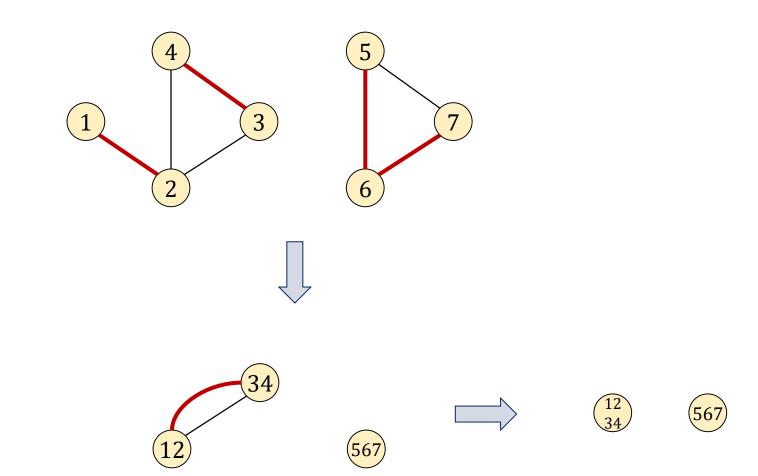
Connectivity via Sketches



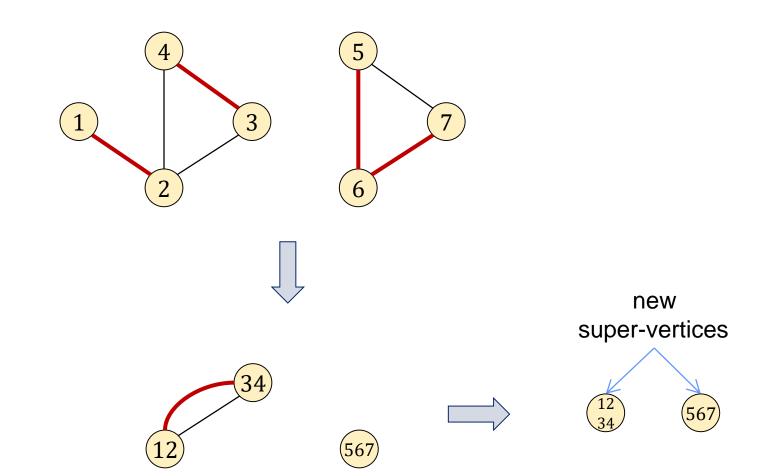
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Finds the connected components of *G*, and a spanning forest, in $O(\log n)$ rounds

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To design an algorithm that uses sketches we have to:

- 1. Define an appropriate graph representation
- 2. Apply ℓ_0 -sampling via linear sketches

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ℓ_0 -sampling

Let K = polylog(N). There is a distribution over matrices $M \in \mathbb{R}^{K \times N}$ such that for any $x \in \mathbb{R}^N$, a random non-zero element of x can be reconstructed from Mx with high probability.

Connectivity via Sketches

To design an algorithm that uses sketches we have to:

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For each vertex v_i we define a vector $\mathbf{a}^i \in \{-1,0,1\}^{\binom{n}{2}}$

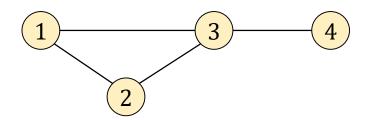
with entries

$$\boldsymbol{a}_{(j,k)}^{i} = \begin{cases} +1, \text{ if } i = j < k \text{ and } (v_j, v_k) \in E \\ -1, \text{ if } j < k = i \text{ and } (v_j, v_k) \in E \\ 0, \text{ otherwise} \end{cases}$$

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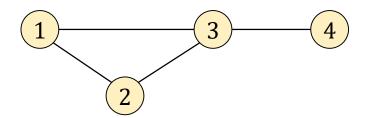


Vector of vertex *i*: $a^{i} = (a^{i}_{(1,2)}, a^{i}_{(1,3)}, a^{i}_{(1,4)}, a^{i}_{(2,3)}, a^{i}_{(2,4)}, a^{i}_{(3,4)})^{T}$

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For any subset of vertices $U \subseteq V$, let $a(U) = \sum_{v_i \in U} a^i$

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The non-zero entries of a(U) correspond to $\delta_G(U)$ = the set of edges of G that cross the cut $(U, V \setminus U)$

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Thus $\sum_{v_i \in U} M a^i = M(\sum_{v_i \in U} a^i)$ gives a random edge in $\delta_G(U)$

Connectivity via Sketches

Connectivity via Sketches Algorithm I: Compute the Sketches in a Single Pass

- 1. Choose $t = O(\log n)$
- 2. **for** i = 1, 2, ..., n and j = 1, 2, ..., t **do**
- 3. Construct the random projection $M_j a^i$

4. **for**
$$i = 1, 2, ..., n$$
 do

5. Compute
$$A_i(\boldsymbol{f}^{\boldsymbol{v}_i}) = (M_1 \boldsymbol{a}^i) \circ (M_2 \boldsymbol{a}^i) \circ \cdots \circ (M_t \boldsymbol{a}^i)$$

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- Each sketch A_i has dimension O(polylogn)
- Since there are n sketches, the required space is O(n polylogn)

Connectivity via Sketches

Connectivity via Sketches Algorithm II: Emulate Connectivity Algorithm

- 1. Let $\hat{V} = V$ be the initial set of super-vertices
- 2. **for** i = 1, 2, ..., t **do**
- 3. **for** each super-vertex $U \in \hat{V}$ **do**
- 4. use $\sum_{v_i \in U} M a^i$ to sample an edge between *U* and another super-vertex *W*
- 5. collapse *U* and *W* to form a new super-vertex

Connectivity via Sketches

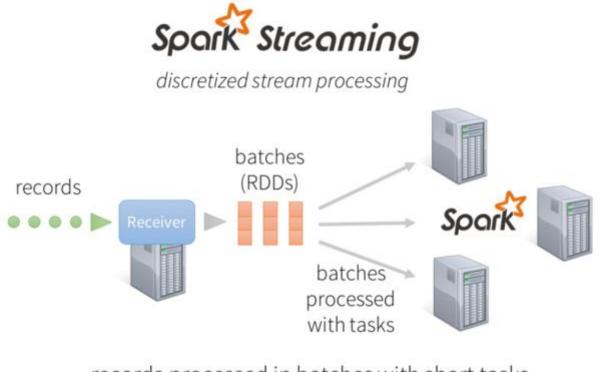
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The update time (to process the next edge in *S*) is O(polylog*n*)

Concluding remarks

- Many graph algorithms in the data stream model are known for basic problems. E.g., estimating connectivity, approximating distances, finding approximate matchings, counting subgraphs,...
- But limited work on directed graphs!
- Space constraints: semi-stream model not suited for sparse graphs (m = 0(n polylogn))

Streaming Architectures

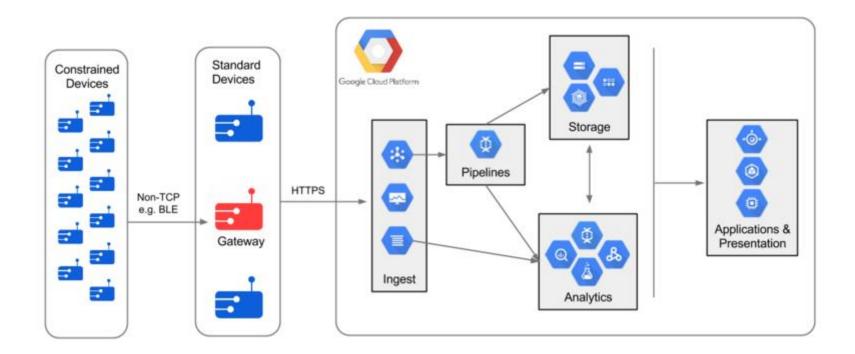


records processed in batches with short tasks each batch is a RDD (partitioned dataset)

Picture from https://databricks.com/blog/2015/07/30/diving-into-spark-streamings-execution-model.html

Streaming Architectures

Google Cloud Platform



https://cloud.google.com/solutions/architecture/streamprocessing